

```

(* PARABOLA *)

(* polinomul de gradul al doilea care genereaza parabola *)

P[x_, y_] := 9 x^2 - 6 x y + y^2 + 20 x;

(* coeficientii formeii patratice *)

a11 = Coefficient[P[x, y], x^2];
a12 = Coefficient[P[x, y], x y] / 2;
a22 = Coefficient[P[x, y], y^2];

A = {{a11, a12}, {a12, a22}};

MatrixForm[A]


$$\begin{pmatrix} 9 & -3 \\ -3 & 1 \end{pmatrix}$$


(* avem gen parabolic *)

δ = Det[A]

0

(* I1 este urma matricii A; simbolul I este protejat *)

I1 = Tr[A]

10

a10 = Coefficient[Coefficient[P[x, y], x], y, 0] / 2;
a20 = Coefficient[Coefficient[P[x, y], y], x, 0] / 2;
a00 = Coefficient[Coefficient[P[x, y], x, 0], y, 0];

(*
    Simbolul D este protejat, foloses DP
*)

DP = {{a11, a12, a10}, {a12, a22, a20}, {a10, a20, a00}}
{{9, -3, 10}, {-3, 1, 0}, {10, 0, 0}}

MatrixForm[DP]


$$\begin{pmatrix} 9 & -3 & 10 \\ -3 & 1 & 0 \\ 10 & 0 & 0 \end{pmatrix}$$


(* avem nedegenerare *)

Δ = Det[DP]

-100

(* Invariantul urmator intra in joc doar daca Δ=0 !!! *)

Δ1 = δ + Det[{{a11, a10}, {a10, a00}}] + Det[{{a22, a20}, {a20, a00}}]

-100

(* autovalorile si vectorii proprii matricii A ; una este 0 *)

λ = Eigenvalues[A];

```

```

λ1 = λ[[1]]
λ2 = λ[[2]]
10
0

vect = Eigenvectors[A];

nr1 = Sqrt[vect[[1]].vect[[1]]];
nr2 = Sqrt[vect[[2]].vect[[2]]];

v1 = vect[[1]] / nr1
v2 = vect[[2]] / nr2

 $\left\{-\frac{3}{\sqrt{10}}, \frac{1}{\sqrt{10}}\right\}$ 

 $\left\{\frac{1}{\sqrt{10}}, \frac{3}{\sqrt{10}}\right\}$ 

(* Vreau ca valoarea proprie 0 sa fie λ1 *)

{λ1, λ2, v1, v2} = If[λ1 == 0, {λ1, λ2, v1, v2}, {λ2, λ1, v2, v1}]

 $\{0, 10, \left\{\frac{1}{\sqrt{10}}, \frac{3}{\sqrt{10}}\right\}, \left\{-\frac{3}{\sqrt{10}}, \frac{1}{\sqrt{10}}\right\}\}$ 

(* orientarea *)

or = Det[{v1, v2}]

1

(*
    Daca orientarea eset negativa schimb semnul la v2
*)

w2 = If[or > 0, v2, -v2];
v2 = w2

 $\left\{-\frac{3}{\sqrt{10}}, \frac{1}{\sqrt{10}}\right\}$ 

(* varful parabolei *)

eq1 = D[P[x, y], x]
eq2 = D[P[x, y], y]
20 + 18 x - 6 y
- 6 x + 2 y

sol = Solve[{eq1 == a v1[[1]], eq2 == a v1[[2]], P[x, y] == 0}, {x, y, a}]

 $\left\{\left\{x \rightarrow -\frac{9}{20}, y \rightarrow \frac{33}{20}, a \rightarrow 2\sqrt{10}\right\}\right\}$ 

x0 = x /. sol[[1]];
y0 = y /. sol[[1]];

r = 0.04;

```

```

varf = ParametricPlot[{x0, y0} + r {Cos[t], Sin[t]},
  {t, 0, 2 Pi}, PlotStyle → {Black, Thickness[0.01]};

(* focarul : se foloseste axa focala definita mai inainte *)

F = ParametricPlot[{x0, y0} + c v + r {Cos[t], Sin[t]},
  {t, 0, 2 Pi}, PlotStyle → {Purple, Thickness[0.005]};

axa1 = ParametricPlot[{x0, y0} + t v1,
  {t, -4, 2}, AspectRatio → Automatic, PlotStyle → Red];
axa2 = ParametricPlot[{x0, y0} + t v2, {t, -4, 2},
  AspectRatio → Automatic, PlotStyle → Red];

VX = Graphics[Arrow[{x0, y0}, {x0, y0} + 1.5 v1]];
VY = Graphics[Arrow[{x0, y0}, {x0, y0} + 1.5 v2]];

axVX = Graphics[{Red, Text["X", {x0, y0} + v1 + {0.5, 0.75}]}];
axVY = Graphics[{Red, Text["Y", {x0, y0} + 2 v2 + {-0.3, 0.25}]}];

varfV = Graphics[{Red, Text["V", {x0, y0} + {0, 0.2}]}];

foc = Graphics[{Purple, Text["F", {x0, y0} + c v + {0, 0.2}]}];

(* reprezentare grafica *)

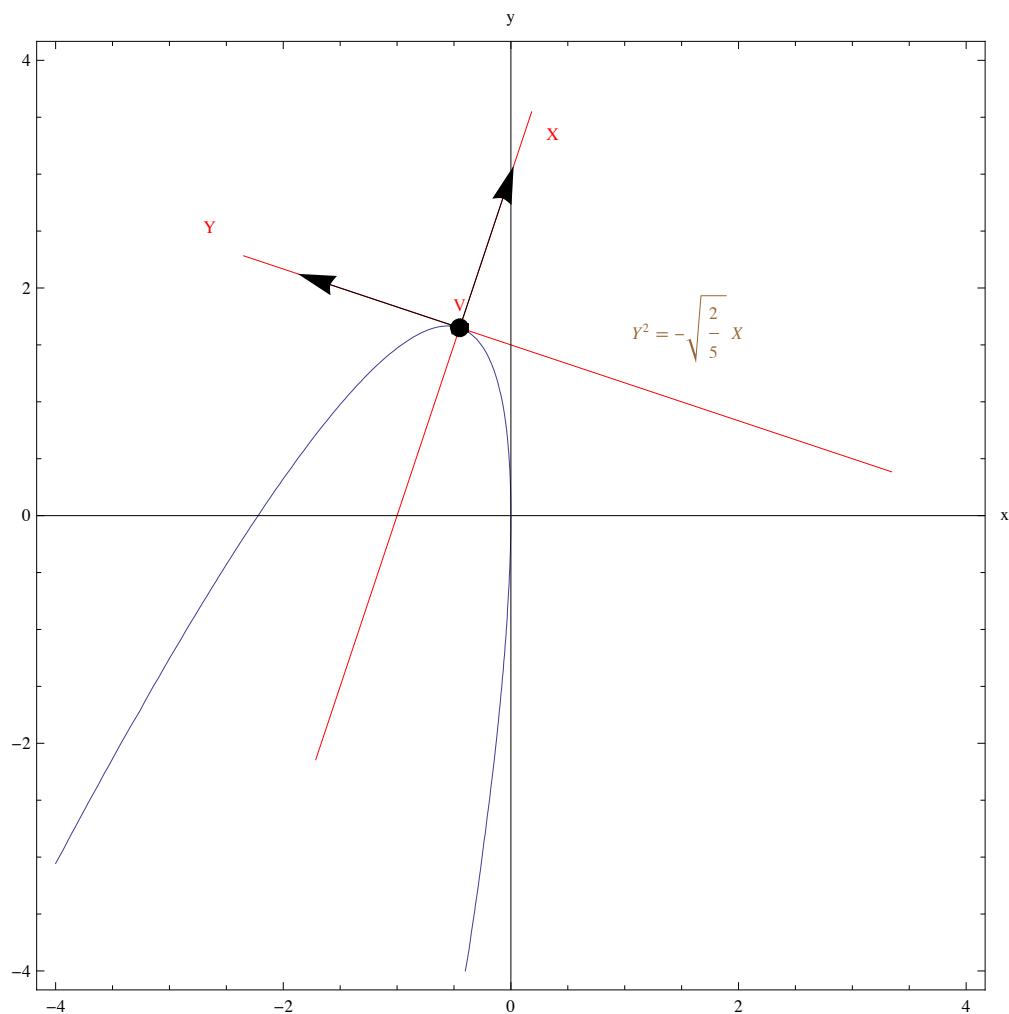
Parabola = ContourPlot[P[x, y] == 0, {x, -4, 4}, {y, -4, 4},
  Axes → True, AxesLabel → {"x", "y"}, AspectRatio → Automatic];

(* p se calculeaza mai jos *)

eqred = Graphics[
  {Brown, Text["Hiperbola:", {x0 - 5, y0 + 5}], Text["Y^2 == 2 p X, {x0 + 2, y0}]}];

```

```
Show[Parabola, axa1, axa2, varf, axVX, axVY, eqred, VX, VY, varfV]
```



```
(* translatia in varful parabolei; scrierea in noile coordonate *)
```

```
(*  
  SCHIMBAREA COORDONATELOR, PENTRU A ADUCE CONICA LA FORMA REDUSA  
*)
```

```
(* ROTATIA : {x, y} --> {xp, yp} *)
```

```
{x, y} = Transpose[{v1, v2}].{xp, yp}
```

$$\left\{ \frac{x_p}{\sqrt{10}} - \frac{3 y_p}{\sqrt{10}}, \frac{3 x_p}{\sqrt{10}} + \frac{y_p}{\sqrt{10}} \right\}$$

```
(* ecuatia elipsei in noile coordonate xp, yp *)
```

```
P1[xp_, yp_] := Simplify[P[x, y]] // Expand
```

```
P1[xp, yp]
```

$$2 \sqrt{10} x_p - 6 \sqrt{10} y_p + 10 y_p^2$$

```
(* A DOUA SCHIMBARE DE COORDONATE *)
```

```
(* refacem coordonatele varfului in noile coordonate xp, yp *)
```

$$\{\mathbf{xp0}, \mathbf{yp0}\} = \{\mathbf{v1}, \mathbf{v2}\} \cdot \{\mathbf{x0}, \mathbf{y0}\}$$

$$\left\{ \frac{9}{2\sqrt{10}}, \frac{3}{\sqrt{10}} \right\}$$

(* FACEM TRANSLATIA IN VARF, centrul noului reper *)

$$\mathbf{xp} = \mathbf{X} + \mathbf{xp0}$$

$$\mathbf{yp} = \mathbf{Y} + \mathbf{yp0}$$

$$\frac{9}{2\sqrt{10}} + X$$

$$\frac{3}{\sqrt{10}} + Y$$

$$\mathbf{P2}[\mathbf{X_}, \mathbf{Y_}] := \text{Simplify}[\mathbf{P1}[\mathbf{xp}, \mathbf{yp}]]$$

$$\mathbf{p} = \frac{-1}{2} \frac{\text{Coefficient}[\mathbf{P2}[\mathbf{X}, \mathbf{Y}], \mathbf{X}]}{\text{Coefficient}[\mathbf{P2}[\mathbf{X}, \mathbf{Y}], \mathbf{Y}, 2]}$$

$$- \frac{1}{\sqrt{10}}$$

```

(* PARABOLA *)

(* polinomul de gradul al doilea care genereaza hparabola *)

P[x_, y_] := 16 x^2 - 24 x y + 9 y^2 - 94 x - 42 y + 205;

(* coeficientii formeii patratice *)

a11 = Coefficient[P[x, y], x^2];
a12 = Coefficient[P[x, y], x y] / 2;
a22 = Coefficient[P[x, y], y^2];

A = {{a11, a12}, {a12, a22}};

MatrixForm[A]

$$\begin{pmatrix} 16 & -12 \\ -12 & 9 \end{pmatrix}$$


(* avem gen hiperbolic *)

δ = Det[A]

0

(* I1 este urma matricii A; simbolul I este protejat *)

I1 = Tr[A]

25

a10 = Coefficient[Coefficient[P[x, y], x], y, 0] / 2;
a20 = Coefficient[Coefficient[P[x, y], y], x, 0] / 2;
a00 = Coefficient[Coefficient[P[x, y], x, 0], y, 0];

(*
    Simbolul D este protejat, foloses DP
*)

DP = {{a11, a12, a10}, {a12, a22, a20}, {a10, a20, a00}}
{{16, -12, -47}, {-12, 9, -21}, {-47, -21, 205}}

MatrixForm[DP]

$$\begin{pmatrix} 16 & -12 & -47 \\ -12 & 9 & -21 \\ -47 & -21 & 205 \end{pmatrix}$$


(* avem nedegenerare *)

Δ = Det[DP]

-50 625

(* Invariantul urmator intra in joc doar daca Δ=0 !!! *)

Δ1 = δ + Det[{{a11, a10}, {a10, a00}}] + Det[{{a22, a20}, {a20, a00}}]

2475

(* autovalorile si vectorii proprii matricii A ; una este 0 *)

λ = Eigenvalues[A];

```

```

λ1 = λ[[1]]
λ2 = λ[[2]]
25
0

vect = Eigenvectors[A];

nr1 = Sqrt[vect[[1]].vect[[1]]];
nr2 = Sqrt[vect[[2]].vect[[2]]];

v1 = vect[[1]] / nr1
v2 = vect[[2]] / nr2

 $\left\{-\frac{4}{5}, \frac{3}{5}\right\}$ 

 $\left\{\frac{3}{5}, \frac{4}{5}\right\}$ 

(* Vreau ca valoarea proprie 0 sa fie λ1 *)

{λ1, λ2, v1, v2} = If[λ1 == 0, {λ1, λ2, v1, v2}, {λ2, λ1, v2, v1}]

 $\left\{0, 25, \left\{\frac{3}{5}, \frac{4}{5}\right\}, \left\{-\frac{4}{5}, \frac{3}{5}\right\}\right\}$ 

(* orientarea *)

or = Det[{v1, v2}]

1

(*
    Daca orientarea eset negativa schimb semnul la v2
*)

w2 = If[or > 0, v2, -v2];
v2 = w2

 $\left\{-\frac{4}{5}, \frac{3}{5}\right\}$ 

(* varful parabolei *)

eq1 = D[P[x, y], x]
eq2 = D[P[x, y], y]
-94 + 32 x - 24 y
-42 - 24 x + 18 y

sol = Solve[{eq1 == a v1[[1]], eq2 == a v1[[2]], P[x, y] == 0}, {x, y, a}]
{{x → 2, y → 1, a → -90}}

x0 = x /. sol[[1]];
y0 = y /. sol[[1]];

r = 0.04;

varf = ParametricPlot[{x0, y0} + r {Cos[t], Sin[t]},
    {t, 0, 2 Pi}, PlotStyle → {Black, Thickness[0.01]};

```

```

(* focarul : se foloseste axa focala definita mai inainte *)

F = ParametricPlot[{x0, y0} + c v + r {Cos[t], Sin[t]},
  {t, 0, 2 Pi}, PlotStyle → {Purple, Thickness[0.005]};

axa1 = ParametricPlot[{x0, y0} + t v1,
  {t, -4, 2}, AspectRatio → Automatic, PlotStyle → Red];
axa2 = ParametricPlot[{x0, y0} + t v2, {t, -4, 2},
  AspectRatio → Automatic, PlotStyle → Red];

VX = Graphics[Arrow[{x0, y0}, {x0, y0} + 1.5 v1]];
VY = Graphics[Arrow[{x0, y0}, {x0, y0} + 1.5 v2]];

axVX = Graphics[{Red, Text["X", {x0, y0} + v1 + {0.5, 0.75}]}];
axVY = Graphics[{Red, Text["Y", {x0, y0} + 2 v2 + {-0.3, 0.25}]}];

varfV = Graphics[{Red, Text["V", {x0, y0} + {0, 0.2}]}];

foc = Graphics[{Purple, Text["F", {x0, y0} + c v + {0, 0.2}]}];

(* reprezentare grafica *)

Parabola = ContourPlot[P[x, y] == 0, {x, -4, 4}, {y, -4, 4},
  Axes → True, AxesLabel → {"x", "y"}, AspectRatio → Automatic];

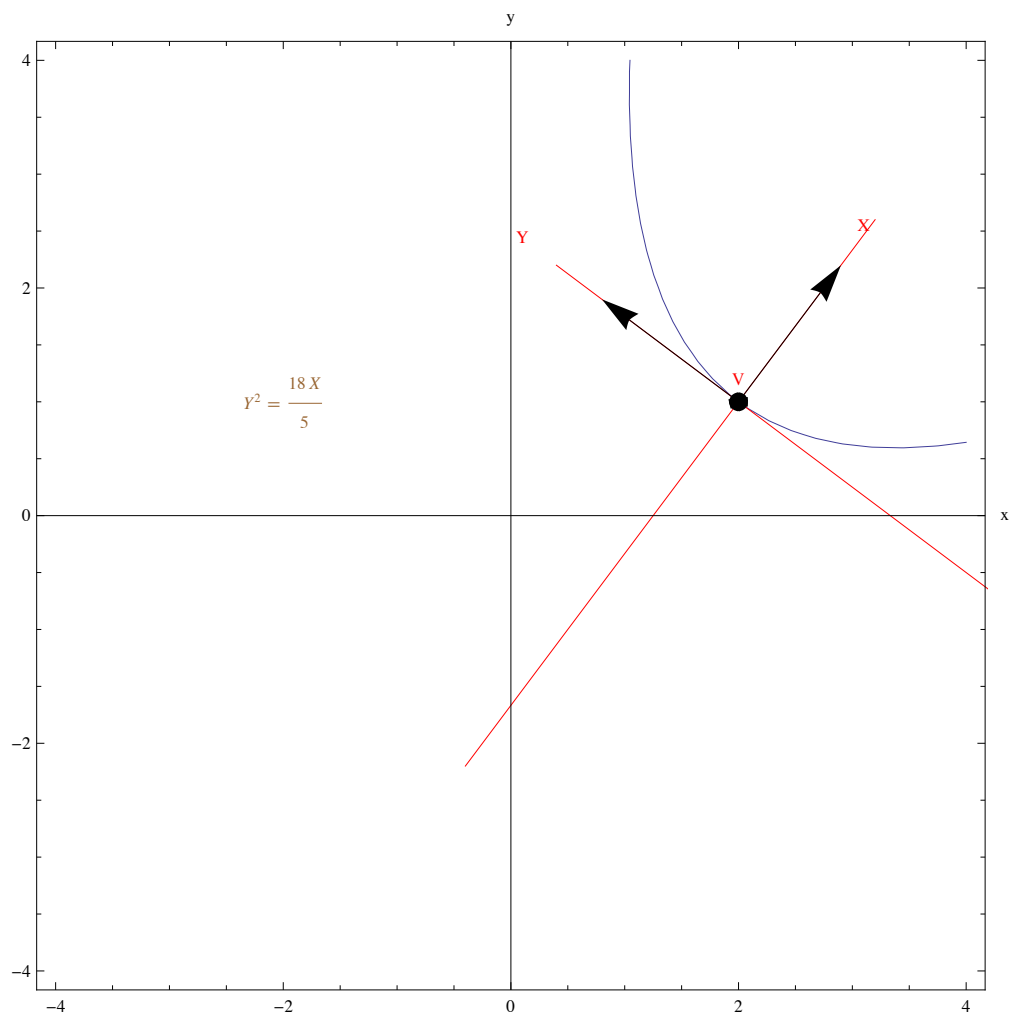
(* p se calculeaza mai jos *)

eqred = Graphics[
  {Brown, Text["Hiperbola:", {x0 - 5, y0 + 5}], Text[ $Y^2 = 2 p X$ , {x0 - 4, y0}]}];

```



```
Show[Parabola, axa1, axa2, varf, axVX, axVY, eqred, VX, VY, varfV]
```



```
(* translatia in varful parabolei; scrierea in noile coordonate *)
```

```
(*  
  SCHIMBAREA COORDONATELOR, PENTRU A ADUCE CONICA LA FORMA REDUSA  
*)
```

```
(* MAI INTAI TRANSLATIA IN VERF, centrul noului reper  
  {x,y} --> {xp,yp}
```

```
*)
```

```
x = xp + x0
```

```
y = yp + y0
```

```
2 + xp
```

```
1 + yp
```

```
P1[xp_, yp_] := Simplify[P[x, y]]
```

```
P1[xp, yp] // Expand
```

```
- 54 xp + 16 xp^2 - 72 yp - 24 xp yp + 9 yp^2
```

```
(* ROTATIA : {xp, yp} --> {X, Y} *)
```

```
{xp, yp} = Transpose[{v1, v2}].{X, Y}
```

$$\left\{ \frac{3X}{5} - \frac{4Y}{5}, \frac{4X}{5} + \frac{3Y}{5} \right\}$$

```
(* ecuatia elipsei in noile coordonate xp, yp *)
```

```
P2[X_, Y_] := Simplify[P1[xp, yp]] // Expand
```

```
P2[X, Y]
```

$$-90X + 25Y^2$$

$$p = \frac{-1}{2} \frac{\text{Coefficient}[P2[X, Y], X]}{\text{Coefficient}[P2[X, Y], Y, 2]}$$

$$\frac{9}{5}$$