

```
(*
interpolare Lagrange - forma parametrica
comportamentul la translatii, rotatii
*)
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```
In[ ]:= t0 = 0;
t1 = 1 / 2;
t2 = 1;
```

```
In[ ]:= Lt0[t_] := 
$$\frac{(t - t1) (t - t2)}{(t0 - t1) (t0 - t2)};$$

Lt1[t_] := 
$$\frac{(t - t0) (t - t2)}{(t1 - t0) (t1 - t2)};$$

Lt2[t_] := 
$$\frac{(t - t0) (t - t1)}{(t2 - t0) (t2 - t1)};$$

```

```
In[ ]:= x0 = 1; y0 = 1;
x1 = 2; y1 = 2;
x2 = -1; y2 = 3;
```

```
In[ ]:= Lt[t_] := Lt0[t] {x0, y0} + Lt1[t] {x1, y1} + Lt2[t] {x2, y2}
```

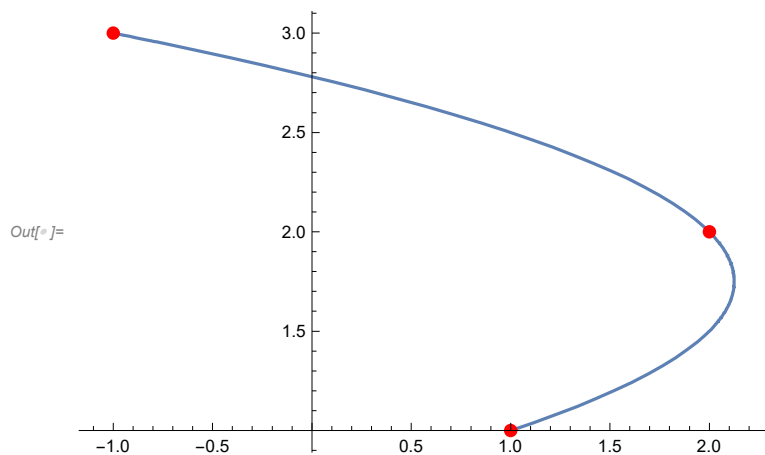
```
In[ ]:= Lt[t_] // Expand
```

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Out[ ]:= {1 + 6 t - 8 t^2, 1 + 2 t}
```

```
In[ ]:= c1 = ParametricPlot[Lt[t], {t, t0, t2}];
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```
In[ ]:= PA = Graphics[{Red, PointSize[Large], Point[{x0, y0}]}];
PB = Graphics[{Red, PointSize[Large], Point[{x1, y1}]}];
PC = Graphics[{Red, PointSize[Large], Point[{x2, y2}]}];
```

```
In[ ]:= Show[c1, PA, PB, PC]
```



```
In[ ]:= a = 1; b = -1;
```

```

In[ ]:= u0 = x0 + a;
        u1 = x1 + a;
        u2 = x2 + a;

In[ ]:= w0 = y0 + b;
        w1 = y1 + b;
        w2 = y2 + b;

In[ ]:= Lt[t_] := Lt0[t] {u0, w0} + Lt1[t] {u1, w1} + Lt2[t] {u2, w2}

In[ ]:= c2 = ParametricPlot[Lt[t], {t, t0, t2}, PlotStyle -> Magenta];

In[ ]:= PA = Graphics[{Green, PointSize[Large], Point[{u0, w0}]}];
        PB = Graphics[{Green, PointSize[Large], Point[{u1, w1}]}];
        PC = Graphics[{Green, PointSize[Large], Point[{u2, w2}]}];

In[ ]:= linie = ParametricPlot[{x, 2}, {x, -1, 4}, PlotStyle -> White];

In[ ]:= Show[linie, c1, PA, PB, PC, c2, PAT, PBT, PCT]

```

Out[]:=

