

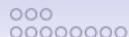


New Finsler metrics of constant curvature

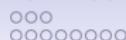
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Finsler metric

Proposition

A Finsler metric on a manifold M is a function $F : TM \rightarrow [0; \infty)$ with following properties:

- ① Smoothness: $F(x; y)$ is C^∞ on $T_0 M$.
- ② Homogeneity: $F(x; \lambda y) = \lambda F(x; y); \lambda > 0$
- ③ Regularity/Convexity: $(g_{ij}(x, y))$ is positive definite, where

$$g_{ij}(x, y) = \frac{1}{2}[F^2]_{y^i y^j}(x, y)$$



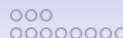
Examples of Finsler structures

- a) *Riemannian metrics*: $F(x, y) = \sqrt{g_{ij}(x)y^i y^j}$, g_{ij} is independent of y .
- b) *Randers metrics* are special members of Finsler metrics which have the form

$$F(x, y) = a + b = \sqrt{a_{ij}(x)y^i y^j} + b_i(x)y^i.$$

It was introduced by Randers in his study of general relativity([Randers-1941]). G. Randers used this metric to describe the asymmetrical space-time. It is an important model in physics.

- c) *Square metrics*: $F = \frac{(a + b)^2}{a}$, where a and b are the quantities from the definition of a Randers metric.



The arc length

Let $F = F(x, y)$ a Finsler metric on a manifold M^n and $\gamma : [a, b] \rightarrow \mathbb{R}$ a smooth curve on M

1 Its arc length is the integral:

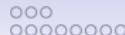
$$L(\gamma) = \int_{\gamma} F(\gamma, \dot{\gamma}) dt. \quad (1)$$

② The First variation of the arc length is:

$$\delta L(\gamma)(V) = - \int_{\gamma} g_{\dot{\gamma}} \left(V, \nabla_{\dot{\gamma}} \frac{\dot{\gamma}}{F(\dot{\gamma})} \right) dt \quad (2)$$

Remark

The first variation leads us to the geodesic equations associated to this metric.



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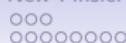
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The variational problem

A geodesic of the manifold (M, F) (parameterized by the arc length) is a critical curve of the energy function:

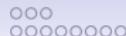
$$E(\gamma) = \int_a^b F^2(\gamma, \dot{\gamma}) ds.$$

Replacing the energy function by $E = F^2$ it follows :

$$\frac{\partial E}{\partial x^i} - \frac{d}{dt} \left(\frac{\partial E}{\partial y^i} \right) = -2g_{ij} \left(\frac{d^2 x^j}{dt^2} + \frac{1}{2} g^{jl} \left(\frac{\partial^2 E}{\partial y^l \partial x^k} - \frac{\partial E}{\partial x^l} \right) \right) = 0. \quad (3)$$

If we denote $G^j(x, y) = \frac{1}{4} g^{jl} \left(\frac{\partial^2 E}{\partial y^l \partial x^k} - \frac{\partial E}{\partial x^l} \right)$, we have a system of n homogeneous differential equations of second order :

$$\frac{d^2 x^i}{dt^2} + 2G^i \left(x, \frac{dx}{dt} \right) = 0. \quad (4)$$



Riemann curvature

The system (4) can be identified with a vector field given by:

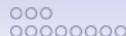
$$S \left(\frac{\partial E}{\partial y^i} \right) + \frac{\partial E}{\partial x^i} = 0,$$

where

$$S = y^i \frac{\partial}{\partial x^i} - 2G^i(x, y) \frac{\partial}{\partial y^i} \quad (5)$$

The vector field written above is called geodesic spray. There are two canonical structures on TM , which we will use to develop our setting. One is the tangent structure, J , and the other one is the Liouville vector field, \mathcal{C} , locally given by

$$J = \frac{\partial}{\partial y^i} \otimes dx^i, \quad \mathcal{C} = y^i \frac{\partial}{\partial y^i}$$



Remark

It is well known that a spray induces a nonlinear connection, $\Gamma = [J, S]$, with the corresponding projectors h and v given by

$$h := \frac{1}{2}(I + \Gamma), \quad v := \frac{1}{2}(I - \Gamma) \quad (6)$$

and the curvature tensor

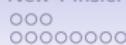
$$R := -\frac{1}{2}[h, h].$$

We introduce the Jacobi endomorphism (the Riemann curvature tensor):

$$R_{(x,y)} := R_k^i(x, y) \frac{\partial}{\partial y^i} \otimes dx^k, \quad (7)$$

where

$$R_k^i = 2 \frac{\partial G^i}{\partial x^k} - S \left(\frac{\partial G^i}{\partial y^k} \right) - \frac{\partial G^i}{\partial y^j} \frac{\partial G^j}{\partial y^k}.$$



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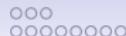
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Flag curvature

Entirely analogous to the Riemannian case, we can define a quantity, that is the corespondant of the sectional curvature, named *flag curvature*.

The main instruments are:

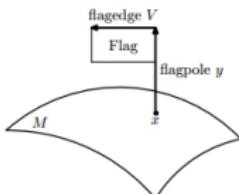
- a point $x \in M$ that will be the place of fixing the flag,
- a flagpole given by a nonzero $y \in T_x M$, and
- an edge $V \in T_x M$ transverse to the flagpole.

$$K(x, y, V) := \frac{g_{(x,y)}(R_{(x,y)}(V), V)}{g_{(x,y)}(y, y)g_{(x,y)}(V, V) - g_{(x,y)}(y, V)^2}, \quad (8)$$

is the *flag curvature* of (y, P) with $P = \text{span}\{y, V\} \subset T_x M$.



Sectional curvature

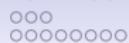


Remark

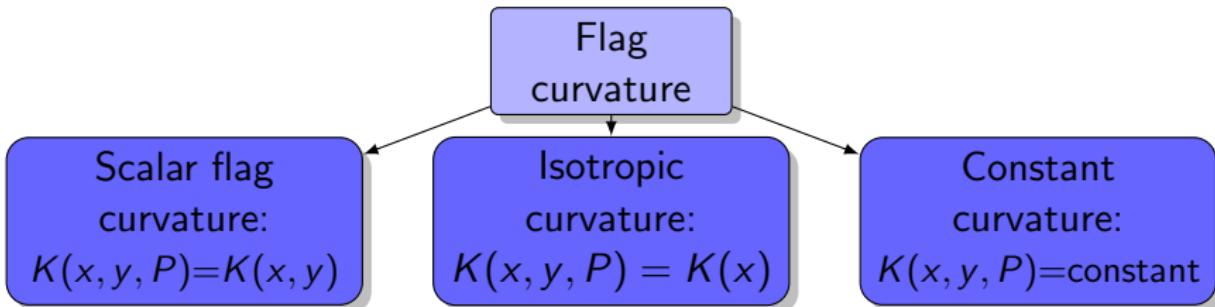
It is well known that the curvature of the flag (y, P) is independent of the choice of the flagedge V . Hence the flag curvature is usually denoted by

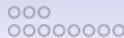
$$K(x, y, V) := K(x, y, P)$$

Contrast to the Riemannian case, the section P cannot completely determine the curvature in Finslerian case. One should pick a flagpole $y \in P$ to construct a flag (P, y) , and then deduce the curvature.



Special flag curvatures





Jacobi endomorphism

Due to the homogeneity of the spray S , information on curvature can also be obtained through the Jacobi endomorphism, which is a 1-vector valued form defined by:

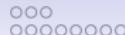
$$\Phi = v \circ [S, h] = R_j^i \frac{\partial}{\partial y^i} \otimes dx^j. \quad (9)$$

Definition

The spray S is isotropic if the Jacobi endomorphism has the following form

$$\Phi = \rho J - \alpha \otimes C \Leftrightarrow R_k^i = \rho \delta_k^i - \alpha_k y^i \Leftrightarrow R_k^i = K F^2 (\delta_k^i - F^{-2} g_{kq} y^q y^i),$$

where $\rho \in C^\infty(T_0 M)$ and $\alpha = \alpha_i(x, y) dx^i \in \Lambda^1(T_0 M)$.



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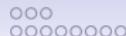
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Projectively related sprays

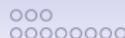
A reparameterization preserving orientation $t \rightarrow \tilde{t}(t)$ of the system

$$\frac{d^2x^i}{dt^2} + 2G^i\left(x, \frac{dx^i}{dt}\right) = 0,$$

leads to a new spray $\tilde{S} = S - 2P\mathcal{C}$.

The scalar function $P \in C^\infty(TM - \{0\})$ is 1-homogeneous and it is related to the new parameter by

$$\frac{d^2\tilde{t}}{dt^2} = P\left(x^i(t), \frac{dx^i}{dt}\right) \frac{d\tilde{t}}{dt}, \quad \frac{d\tilde{t}}{dt} > 0. \quad (10)$$



Projectively related sprays

Definition

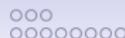
Two sprays S and \tilde{S} are *projectively related* if their geodesics coincide up to an orientation preserving reparameterization.

A Finsler metric is *projectively flat* if and only if it satisfies the Hamel equation:

$$\delta_{S_0} F = d_J S_0 F - 2d_{h_0} F = 0. \quad (11)$$

In this case the projective factor $P(x, y)$ is given by

$$P(x, y) = \frac{S_0 F}{2F}. \quad (12)$$



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Weyl-type curvature tensor for Finsler spaces

Definition

Consider S a spray with Jacobi endomorphism Φ and curvature tensor R . We define the following Weyl-type curvature tensors

$$W_0 = \Phi - \frac{1}{n-1} (\text{Tr } \Phi) J + \frac{1}{2(n-1)} d_J (\text{Tr } \Phi) \otimes \mathcal{C}. \quad (13)$$

and

$$W_1 = \frac{1}{3} [J, W_0] = R - \frac{1}{2(n-1)} d_J (\text{Tr } \Phi) \wedge J \quad (14)$$

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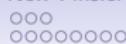
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Finsler metrics of constant flag curvature

Theorem

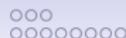
For a Finsler metric on a manifold of $\dim M \geq 3$ the following conditions are equivalent:

- ① The Finsler metric has constant flag curvature.
- ② The Weyl type curvature tensor W_0 vanishes.
- ③ The Weyl type curvature tensor W_1 vanishes.

Theorem

A Finsler metric on a 2-dimensional manifold has constant flag curvature if and only if the following conditions are satisfied

- ① The Weyl-type tensor (14) vanishes.
- ② $d_h\alpha = 0$.



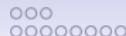
Projectively related Weyl-type curvature tensors

Lemma

Consider $\tilde{S} = S - 2P\mathcal{C}$ two projectively related sprays. The corresponding Weyl-curvature tensor W_1 are related by

$$\tilde{W}_1 = W_1 + \frac{1}{2}\delta_S P \wedge J + d_J d_h P \otimes \mathcal{C}. \quad (15)$$

The Weyl-type curvature tensor W_1 is projectively invariant if and only if the projective factor associated to the deformation satisfies $\delta_S P = 0$ and hence is a Hamel function.



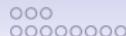
Lemma

Consider S and $\tilde{S} = S - 2P\mathcal{C}$ two projectively related isotropic sprays with the property that P is a Hamel function. Then the derivatives with respect to the horizontal projector of the semi-basic 1-forms α and $\tilde{\alpha}$ are related by

$$d_h \tilde{\alpha} = d_h \alpha - d_R P - P d_J \alpha + \alpha \wedge d_J P. \quad (16)$$

Proposition

We consider F and \tilde{F} two projectively related Finsler metrics. If the initial metric F is of constant flag curvature and the projective factor is a Hamel function then \tilde{F} is of constant flag curvature.



New condition for isotropic sprays

The curvature tensors Φ and R are related by

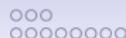
$$3R = [J, \Phi], \quad \Phi = i_S R. \quad (17)$$

Lemma

A spray S is isotropic if and only if there exists a semi-basic 1-form $\xi \in \Lambda^1(T_0 M)$ such that its curvature tensor R is given by:

$$R = \xi \wedge J - d_J \xi \otimes \mathcal{C}, \quad (18)$$

where $\xi = \frac{1}{3}(\alpha + d_J \rho)$.



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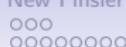
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New Finslerian Version of Schur Lemma

Theorem (Finslerian version of Schur's Lemma for $n \geq 2$)

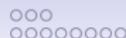
Consider S the geodesic spray of a Finsler metric F . Then F has constant curvature if and only if:

S is isotropic (this condition is always true for $n=2$); (19)

and the curvature 1-form satisfies:

$$d_J \xi = 0; \quad (20)$$

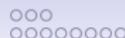
$$d_h \xi = 0 \quad (\text{this condition is always true for } n \geq 3). \quad (21)$$



Finslerian Version of Beltrami Theorem

Theorem (Finslerian version of Beltrami's Theorem for $n \geq 2$)

Consider F and \tilde{F} two projectively related Finsler metrics. If \tilde{F} has constant curvature then F has also constant curvature if and only if the projective factor P is a Hamel function.



Projectively flat Randers metrics

Proposition

A Randers metric $F = a + b$ is projectively flat if and only if the Riemannian metric a is projectively flat and the 1-form $b;dx^i$ is closed.

Lemma

Let $F = \sqrt{g_{ij}(x)y^i y^j}$ be a positive definite Finsler metric on an open domain (open and convex) $\mathcal{U} \subset \mathbb{R}^n$ that is reducible to a Riemannian metric. Then F is projectively flat if and only if the following relation is satisfied

$$g_{ij,I} = 2\psi_I g_{ij} + \psi_i g_{jl} + \psi_j g_{il}, \quad P(x, y) = \psi_I(x)y^I. \quad (22)$$

In this case, P is the projective factor of F .



Projectively flat Randers metrics

The family of projectively flat Finsler metrics that are reducible to a Riemannian metric is given by:

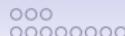
$$F = \frac{\sqrt{|y|^2 + \mu(|x|^2|y|^2 - \langle x, y \rangle^2)}}{1 + \mu|x|^2}. \quad (23)$$

Lemma

The family of projectively flat Randers metrics of negative constant flag curvature whose projective factor is proportional to the metric is given by $F = a + b$, where:

$$a = \frac{\sqrt{|y|^2 - 4c^2(|x|^2|y|^2 - \langle x, y \rangle^2)}}{1 - 4c^2|x|^2} \text{ and } b = \frac{2c\langle x, y \rangle}{1 - 4c^2|x|^2}. \quad (24)$$

In this case, the constant c represents the coefficient of proportionality between the projective factor and the metric.



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A new family of projectively related Finsler metrics obtained through a Randers deformation

We consider F given by (24). We make a Randers deformation of the metric

$$F \rightarrow \tilde{F} = F + \tilde{b}, \quad (25)$$

where \tilde{b} is given by $\tilde{b}(x, y) = b_i(x)y^i$. Since $\delta_S \tilde{F} = 0 \Leftrightarrow \delta_S \tilde{b} = 0$, it follows that F and \tilde{F} are projectively related.

The projective factor is given by:

$$P = \frac{S(\tilde{F})}{2\tilde{F}} = \frac{S(F + \tilde{b})}{2(F + \tilde{b})} = \frac{S(\tilde{b})}{2(F + \tilde{b})}. \quad (26)$$



New families of Finsler metrics of negative flag curvature

We assume that $P = \nu \tilde{b}$, $\nu \in \mathbb{R}$ and we get

$$S_0 \tilde{b} - 2\nu \tilde{b}^2 = 0. \quad (27)$$

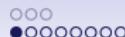
Finally we got that the 1-form \tilde{b} is given by

$$\tilde{b}(x, y) = \frac{\langle e, y \rangle}{4\nu^2 (\langle e, x \rangle + f)}, f > 0, |e| < 1. \quad (28)$$

Therefore, the metric obtained through this deformation is

$$\tilde{F} = \frac{\sqrt{|y|^2 - 4\nu^2 (|x|^2|y|^2 - \langle x, y \rangle^2)}}{1 - 4\nu^2|x|^2} - \frac{2\nu \langle x, y \rangle}{1 - 4\nu^2|x|^2} + \frac{\langle e, y \rangle}{4\nu^2 (\langle e, x \rangle + f)}, \quad (29)$$

with $\tilde{\kappa} = -c^2$.



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New Finsler metrics of zero flag curvature inspired by squared metrics

We consider the following deformation of the Finsler metric (24):

$$\tilde{F} = f(x) \frac{F^2}{a}, \text{ where } f \text{ is a positive function and } a \text{ is given by (24).} \quad (30)$$

Lemma

Let $F = a + b$ a Randers metric. Then $\tilde{F} = f(x) \frac{F^2}{a}$ is projectively related to F if and only if the following relation is satisfied

$$\frac{F^2}{a} d_h f - S(f) d_J \left(\frac{F^2}{a} \right) + f S(a) d_J \left(\frac{F^2}{a^2} \right) = 0. \quad (31)$$



A new Finsler metric of zero flag curvature

$$P = \frac{S(f)}{2f} - \frac{S_0 a - 2cFa}{2a} = \frac{Sf}{2f} - \frac{4cab - 2cFa}{2a} = \frac{S_0 f}{2f} - 2cb + cF. \quad (32)$$

We notice that

$$\delta_S P = \delta_S \left(\frac{S_0 f}{2f} - 2cb + cF \right) = \delta_S \left(\frac{S_0 f}{2f} \right) \quad (33)$$

We assume that $S_0 f = 4cfb$ and we get

$$\tilde{F} = \frac{\eta(\sqrt{|y|^2 - 4c^2(|x|^2|y|^2 - \langle x, y \rangle^2)} + 2c\langle x, y \rangle)^2}{(1 - 4c^2|x|^2)^2 \sqrt{|y|^2 - 4c^2(|x|^2|y|^2 - \langle x, y \rangle^2)}}, \quad \eta \in \mathbb{R}^+, \quad (34)$$

with $\tilde{\kappa} = 0$.



A new metric of zero flag curvature obtained through a conformal transformation

Lemma

We consider F and \tilde{F} two projectively flat Finsler metrics and

$\bar{F} = g(x)\tilde{F} + \frac{f(y)}{F}\tilde{F}$ a metric obtained by a multiplication of the projectively flat metric \tilde{F} with the 0-homogeneous function

$g(x) + \frac{f(y)}{F}$, where g and f are considered such that \tilde{F} is positive.

Then \bar{F} is projectively flat if and only if the following relation is satisfied

$$\begin{aligned}
 & \tilde{F}d_{h_0}g - S_0gd_J\tilde{F} - \frac{S_0fd_J\tilde{F}}{F} + \frac{\tilde{F}S_0fd_JF}{F^2} - \frac{S_0\tilde{F}d_Jf}{F} + \frac{fS_0\tilde{F}d_JF}{F^2} + \frac{\tilde{F}S_0Fd_Jf}{F^2} \\
 & + \frac{fS_0Fd_J\tilde{F}}{F^2} - \frac{2f\tilde{F}S_0Fd_JF}{F^3} = 0.
 \end{aligned}
 \tag{35}$$



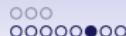
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$$P = \frac{S_0 \bar{F}}{2\tilde{F}} = \frac{S_0 g \cdot \tilde{F} + g S_0 \tilde{F} + \frac{S_0 f}{F} \tilde{F} + \frac{f S_0}{F} \tilde{F} - f \frac{\tilde{F}}{F^2} S_0 F}{2 \left(g \tilde{F} + \frac{f}{F} \tilde{F} \right)} \quad (36)$$

We recall that F and \tilde{F} are two projectively flat Finsler metrics for which $S_0 F = 2cF^2$ and $S_0 \tilde{F} = 4cF\tilde{F}$.

Therefore, (36) becomes:

$$P = \frac{S_0 g \cdot \tilde{F} + \frac{S_0 f}{F} \tilde{F} - 2cf \tilde{F}}{2 \left(g \tilde{F} + \frac{f}{F} \tilde{F} \right)} + 2cF. \quad (37)$$



New Finsler metric of zero flag curvature

Taking into account the conditions imposed on the functions f and g it follows that we can make the following extra assumption

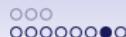
$$S_0g = 2cf \text{ and } S_0f = 0. \quad (38)$$

With the assumptions considered in (38) we get that the projective factor associated is

$$P = 2cF, \quad (39)$$

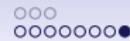
which is a Hamel function. We can write now the expression for the new metric as follows

$$\begin{aligned} \bar{F} = & \frac{\eta(\sqrt{|y|^2 - 4c^2(|x|^2|y|^2 - \langle x, y \rangle^2)} + 2c\langle x, y \rangle)^2}{(1 - 4c^2|x|^2)^2 \sqrt{|y|^2 - 4c^2(|x|^2|y|^2 - \langle x, y \rangle^2)}} \\ & \cdot \left(2c\langle a, x \rangle + e + \frac{\langle a, y \rangle}{\frac{\sqrt{|y|^2 - 4c^2(|x|^2|y|^2 - \langle x, y \rangle^2)}}{1 - 4c^2|x|^2} + \frac{2c\langle x, y \rangle}{1 - 4c^2|x|^2}} \right). \end{aligned} \quad (40)$$



References

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Thank you