

The Gaussian curvature for the indicatrix of a generalized Lagrange space

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Abstract

Using the formulae for the Gaussian curvature of a indicatrix in a Lagrange space from [3] and [6] similar computations are obtained for generalized Lagrange spaces. Some examples are discussed.

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1 The Gaussian curvature for the indicatrix of a Lagrange space

In the n -dimensional Euclidean space \mathbb{R}^n let us consider a hypersurface S defined by $f \in C^\infty(\mathbb{R}^n)$ as: $S = \{x \in \mathbb{R}^n \mid f(x) = 0, \nabla f(x) \neq 0\}$ where ∇f denotes the gradient of f namely $\nabla f = (f_i)$ where $f_i = \frac{\partial f}{\partial x^i}$. Suppose that the normal vector field of S is: $N = -\frac{\nabla f}{\|\nabla f\|}$. In [6, p. 37] and [3, p. 23] the following classical result is proved in a direct way:

Proposition 1.1 *The Gaussian curvature of pair (S, N) is:*

$$K = - \frac{\begin{vmatrix} f_{ij} & f_i \\ f_j & 0 \end{vmatrix}}{\|\nabla f\|^{n+1}}. \quad (1.1)$$

This formulae is used in the cited papers in order to obtain the Gaussian curvature for the indicatrix of a *Lagrange space*. More precisely, let $L : T\mathbb{R}^n \rightarrow \mathbb{R}$ be a regular Lagrangian that is the matrix $g_{ij} = \frac{1}{2} \dot{\partial}_i \dot{\partial}_j L$ is of rank n i. e. $\det(g_{ij}) \neq 0$ where $\dot{\partial}_i = \frac{\partial}{\partial y^i}$. Associated to this Lagrangian we have the *indicatrix of L* : for every $x \in \mathbb{R}^n$, $I_x = \{(x, y) \in T\mathbb{R}^n; L(x, y) = 1\}$ appears as a hypersurface defined by: $f(x, y) = L(x, y) - 1$. Then it is proved in [6, p. 39] that:

Proposition 1.2 *Let (\mathbb{R}^n, L) be a Lagrange space. At each $x \in \mathbb{R}^n$ the Gaussian curvature K_x of the indicatrix I_x oriented in the direction $N_x = -\frac{\dot{\nabla} L}{\|\dot{\nabla} L\|}$ is:*

$$K_x = - \frac{\begin{vmatrix} \dot{\partial}_i \dot{\partial}_j L & \dot{\partial}_i L \\ \dot{\partial}_j L & 0 \end{vmatrix}}{\left(\sum_{i=1}^n (\dot{\partial}_i L)^2\right)^{\frac{n+1}{2}}}. \quad (1.2)$$

In this proposition $\dot{\nabla} L$ denotes the gradient of L with respect to y i.e. $\dot{\nabla} L = (\dot{\partial}_i L)_{1 \leq i \leq n}$.

A function $f \in C^\infty(T\mathbb{R}^n)$ which does not depends on x i.e. $f = f(y)$ is called *Minkowskian function*. A tensor field of (r, s) -type on $T\mathbb{R}^n$ with law of change, at a change of coordinates on $T\mathbb{R}^n$, exactly as a tensor field of (r, s) -type on \mathbb{R}^n is called *d-tensor field of (r, s) -type on $T\mathbb{R}^n$* . We denote $T_0\mathbb{R}^n$ the tangent bundle of \mathbb{R}^n without the null section.

2 The Gaussian curvature for the indicatrix of a generalized Lagrange space

A d-tensor field of $(0, 2)$ -type on $T\mathbb{R}^n$, denoted $(g_{ij}(x, y))$, is called *generalized Lagrange metric (GL-metric, on short)* if has the following properties ([5]):

- (i) symmetry, $g_{ij} = g_{ji}$
- (ii) nondegeneracy, $g := \det(g_{ij}) \neq 0$.

The function $\mathcal{E}(g) = g_{ij}y^i y^j$ is called *the absolute energy* of the given GL-metric.

Definition 2.1([5]) The GL-metric (g_{ij}) is called *weak regular* if $\mathcal{E}(g)$ is a regular Lagrangian.

It follows that for a weak regular GL-metric the d-tensor of $(0, 2)$ -type:

$$g_{ij}^* = \frac{1}{2} \dot{\partial}_i \dot{\partial}_j \mathcal{E}(g) \quad (2.1)$$

is a Lagrange metric and then we can associate the indicatrix

$$I_x = \{(x, y) ; \mathcal{E}(g)(x, y) = 1, \dot{\nabla} \mathcal{E}(g)(x, y) \neq 0\}.$$

Applying proposition 1.2 we get the main result of this paper:

Proposition 2.2 For a weak regular Lagrange metric the Gaussian curvature of I_x is:

$$K_x = - \frac{\begin{vmatrix} g_{ij}^* & \dot{\partial}_i \mathcal{E}(g) \\ \dot{\partial}_j \mathcal{E}(g) & 0 \end{vmatrix}}{\left(\sum_{i=1}^n (\dot{\partial}_i \mathcal{E}(g))^2 \right)^{\frac{n+1}{2}}}. \quad (2.2)$$

A straightforward computation gives:

$$\begin{cases} g_{ij}^* = g_{ij} + \frac{1}{2} (\dot{\partial}_i \dot{\partial}_j g_{ab}) y^a y^b + (\dot{\partial}_i g_{ja} + \dot{\partial}_j g_{ia}) y^a \\ \dot{\partial}_i \mathcal{E}(g) = \frac{1}{2} (\dot{\partial}_i g_{ab}) y^a y^b + g_{ia} y^a \end{cases}. \quad (2.3)$$

The above formulae become more simple in the following case:

Definition 2.3([5]) A weak regular generalized Lagrange metric is called *regular* if:

$$\frac{1}{2} \dot{\partial}_i \mathcal{E}(g) = g_{ij} y^j. \quad (2.4)$$

It results([5]):

$$g_{ij}^* = g_{ij} + (\dot{\partial}_j g_{ik}) y^k \quad (2.5)$$

and then:

$$K_x = - \frac{\begin{vmatrix} g_{ij} + \dot{\partial}_j g_{ik} y^k & 2g_{ik} y^k \\ 2g_{jk} y^k & 0 \end{vmatrix}}{2^{n+1} \left[\sum_{i=1}^n (g_{ik} y^k)^2 \right]^{\frac{n+1}{2}}}. \quad (2.6)$$

Using the notation $y_i = g_{ik}y^k$ a simple form can be given:

$$K_x = - \frac{\begin{vmatrix} g_{ij} + \dot{\partial}_j g_{ik}y^k & 2y_i \\ 2y_j & 0 \end{vmatrix}}{2^{n+1} \left[\sum_{i=1}^n y_i^2 \right]^{\frac{n+1}{2}}}. \quad (2.7)$$

For example $n = 2$ the denominator of (2.6) is:

$$D_x = \begin{vmatrix} g_{11} + \dot{\partial}_1 g_{11}y^1 + \dot{\partial}_1 g_{12}y^2 & g_{12} + \dot{\partial}_2 g_{11}y^1 + \dot{\partial}_2 g_{12}y^2 & 2y_1 \\ g_{12} + \dot{\partial}_1 g_{12}y^1 + \dot{\partial}_1 g_{22}y^2 & g_{22} + \dot{\partial}_2 g_{12}y^1 + \dot{\partial}_2 g_{22}y^2 & 2y_2 \\ 2y_1 & 2y_2 & 0 \end{vmatrix}. \quad (2.8)$$

Let us suppose in addition that the GL-metric is diagonal i. e. $g_{12} = g_{21} = 0$. It follows:

$$\begin{aligned} D_x &= \begin{vmatrix} g_{11} + \dot{\partial}_1 g_{11}y^1 & \dot{\partial}_2 g_{11}y^1 & 2g_{11}y^1 \\ \dot{\partial}_1 g_{22}y^2 & g_{22} + \dot{\partial}_2 g_{22}y^2 & 2g_{22}y^2 \\ 2g_{11}y^1 & 2g_{22}y^2 & 0 \end{vmatrix} = \\ &= 2g_{11}y^1 \left[2y^1y^2 (g_{22} \dot{\partial}_2 g_{11} - g_{11} \dot{\partial}_2 g_{22}) - 2g_{11}g_{22}y^1 \right] - \\ &\quad - 2g_{22}y^2 \left[2y^1y^2 (g_{22} \dot{\partial}_1 g_{11} - g_{11} \dot{\partial}_1 g_{22}) + 2g_{11}g_{22}y^2 \right]. \end{aligned} \quad (2.9)$$

Another approach in the regular case is provided by homogeneity. By multiplication of eq. (2.4) with y^i it results:

$$\left(\dot{\partial}_i \mathcal{E}(g) \right) y^i = 2g_{ij}y^i y^j = 2\mathcal{E}(g) \quad (2.10)$$

which means that $\mathcal{E}(g)$ is 2-homogeneous i. e. $E(g)$ is a Finsler function([5]). But for a Finsler function in [6, p. 40] it is proved:

Proposition 2.4 *Let (\mathbb{R}^n, F) be a Finsler space and $g = \frac{1}{2} \det \left(\dot{\partial}_i \dot{\partial}_j F^2 \right)$. At each point $x \in \mathbb{R}^n$ the Gaussian curvature K_x of the indicatrix I_x oriented in the direction opposite to $\dot{\nabla} L$ is:*

$$K_x = \frac{g}{\left(\sum_{i=1}^n l_i^2 \right)^{\frac{n+1}{2}}} \quad (2.11)$$

where $l_i = \dot{\partial}_i F$.

It follows in our framework:

Proposition 2.5 *If $g = (g_{ij}(x, y))$ is a regular generalized Lagrange metric then the Gaussian curvature K_x of the indicatrix I_x is:*

$$K_x = \frac{g^*}{\left(\sum_{i=1}^n y_i^2\right)^{\frac{n+1}{2}}} \quad (2.12)$$

where $g^* = \det(g_{ij}^*)$.

3 Beil metrics as examples

Let $\tilde{g} = (\tilde{g}_{ij})$ be a Finsler metric and $B = B^i(x, y) \dot{\partial}_i$ a d-vector field for which we denote $B_i = \tilde{g}_{ij} B^j$ and $B_0 = B_i y^i$. Let also $a, b \in C^\infty(TM)$. In [1] and [2] the following GL-metric is studied:

$$g_{ij} = a\tilde{g}_{ij} + bB_i B_j. \quad (3.1)$$

This GL-metrics, called *Beil metrics*, are not Lagrange metrics. Because:

$$\mathcal{E}(g) = a\mathcal{E}(\tilde{g}) + b(B_0)^2 \quad (3.2)$$

we get:

$$\dot{\partial}_i \mathcal{E}(g) = \dot{\partial}_i a \mathcal{E}(\tilde{g}) + a \dot{\partial}_i \mathcal{E}(\tilde{g}) + \dot{\partial}_i b (B_0)^2 + 2b B_0 \dot{\partial}_i B_0 \quad (3.3)$$

$$\begin{aligned} 2g_{ij}^* &= 2\tilde{g}_{ij}^* + \dot{\partial}_i \dot{\partial}_j a \mathcal{E}(\tilde{g}) + \dot{\partial}_i a \dot{\partial}_j \mathcal{E}(\tilde{g}) + \dot{\partial}_j a \dot{\partial}_i \mathcal{E}(\tilde{g}) + \dot{\partial}_i \dot{\partial}_j b (B_0)^2 + \\ &+ 2B_0 \left(\dot{\partial}_i b \dot{\partial}_j B_0 + \dot{\partial}_j b \dot{\partial}_i B_0 + b \dot{\partial}_i \dot{\partial}_j B_0 \right) + 2b \dot{\partial}_i B_0 \dot{\partial}_j B_0. \end{aligned} \quad (3.4)$$

I (**A Beil metric with hypersphere as indicatrix**) On $T_0\mathbb{R}^n$ let:

$$a = \frac{1}{2}, b = \frac{1}{2\|y\|_F^2}, B_i = y_i = \tilde{g}_{ik} y^k \quad (3.5)$$

where $\|\cdot\|_F$ is the norm induced by the Finsler metric \tilde{g} i.e. $\|y\|_F^2 = \mathcal{E}(\tilde{g}) = \tilde{g}_{ij} y^i y^j$. Let us remark that for this choice $B = y^i \dot{\partial}_i$ is exactly *the Liouville vector field* on TM . The considered Beil metric is:

$$g_{ij} = \frac{1}{2\|y\|_F^2} \begin{pmatrix} (y^1)^2 + \|y\|_F^2 & y^1 y^2 & \dots & y^1 y^n \\ y^1 y^2 & (y^2)^2 + \|y\|_F^2 & \dots & y^2 y^n \\ \dots & \dots & \dots & \dots \\ y^1 y^n & y^2 y^n & \dots & (y^n)^2 + \|y\|_F^2 \end{pmatrix}. \quad (3.6)$$

A straightforward computation gives:

$$\mathcal{E}(g) = \|y\|_F^2 \quad (3.7)$$

which is 2-homogeneous and then a Finsler function. It results that (g_{ij}) is a Minkowskian regular generalized metric with:

$$g_{ij}^* = \delta_{ij}, \quad y_i = y^i \quad (3.8)$$

and then applying (2.12):

$$K_x = \frac{1}{\|y\|_F^{n+1}} = 1 \quad (3.9)$$

because we are on the indicatrix $I_x : \|y\|_F^2 = 1$.

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