

## Seminar 19.05.2020

### CONICE PE ECUATII GENERALE

**Ex 1.** Să se studieze și să se reprezinte grafic următoarele conice pe ecuații generale, precizându-se (toate) elementele:

(a)  $3x^2 + 2xy + 3y^2 + 8x - 8y + 8 = 0$

(b)  $7x^2 - 8xy + y^2 - 6x - 12y - 9 = 0.$

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In[1]:= (*
        Folosesc El si nu E, fiindca in Mathematica litera E este protejata
        *)

In[2]:= (* polinomul de gradul al doilea care genereaza conica *)

In[3]:= El[x_, y_] := 3 x^2 + 2 x y + 3 y^2 + 8 x - 8 y + 8;           Fie conica E(x,y)=0

In[4]:= (* coeficientii formei patratice *)

In[5]:= a11 = Coefficient[El[x, y], x^2];
        a12 = Coefficient[El[x, y], x y] / 2;
        a22 = Coefficient[El[x, y], y^2];

In[8]:= (* matricea formei patratice *)

In[9]:= A = {{a11, a12}, {a12, a22}};

In[10]:= MatrixForm[A]
Out[10]/MatrixForm=
      ( 3  1 )
      ( 1  3 )

In[11]:= (* determinam genul conicei . . . *)

In[12]:= δ = Det[A]
Out[12]= 8

In[13]:= (* . . . este pozitiv, deci conica este de gen eliptic *)

In[14]:= (*
        Mai departe IA este I; in Mathematica simbolul I este protejat
        *)

In[15]:= IA = Tr[A]
Out[15]= 6

In[16]:= a10 = Coefficient[Coefficient[El[x, y], x], y, 0] / 2;
        a20 = Coefficient[Coefficient[El[x, y], y], x, 0] / 2;

In[18]:= a00 = Coefficient[Coefficient[El[x, y], x, 0], y, 0];

In[19]:= (*
        Simbolul D este protejat, foloses DE
        *)

In[20]:= DE = {{a11, a12, a10}, {a12, a22, a20}, {a10, a20, a00}}
Out[20]= {{3, 1, 4}, {1, 3, -4}, {4, -4, 8}}

In[21]:= MatrixForm[DE]
Out[21]/MatrixForm=
      ( 3  1  4 )
      ( 1  3 -4 )
      ( 4 -4  8 )

In[22]:= Δ = Det[DE]
Out[22]= -64           diferit de 0, deci nedegenerata

In[23]:= (* autovalorile si vectorii proprii matricii A *)

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In[24]:=  $\lambda = \text{Eigenvalues}[A];$

$$\det(A - \lambda I) = 0$$

In[25]:=  $\lambda_1 = \lambda[[1]]$   
 $\lambda_2 = \lambda[[2]]$

Out[25]= 4

Out[26]= 2

In[27]:=  $\text{vect} = \text{Eigenvectors}[A]$

$$\lambda^2 - 6\lambda + 8 = 0$$

Out[27]=  $\{\{1, 1\}, \{-1, 1\}\}$

In[28]:=  $\text{nr1} = \text{Sqrt}[\text{vect}[[1]] \cdot \text{vect}[[1]]];$   
 $\text{nr2} = \text{Sqrt}[\text{vect}[[2]] \cdot \text{vect}[[2]]];$

In[30]:= **(\* vectori proprii, normalizati \*)**

In[31]:=  $\text{v1} = \text{vect}[[1]] / \text{nr1}$   
 $\text{v2} = \text{vect}[[2]] / \text{nr2}$

Out[31]=  $\left\{ \frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}} \right\}$

Out[32]=  $\left\{ -\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}} \right\}$

In[33]:= **(\* centrul elipsei \*)**

In[34]:=  $\text{eq1} = \text{D}[E1[x, y], x]$   
 $\text{eq2} = \text{D}[E1[x, y], y]$

Out[34]=  $8 + 6x + 2y$

Out[35]=  $-8 + 2x + 6y$

In[36]:=  $\text{sol} = \text{Solve}[\{\text{eq1} == 0, \text{eq2} == 0\}, \{x, y\}]$

Out[36]=  $\{\{x \rightarrow -2, y \rightarrow 2\}\}$

In[37]:= **(\* VEZI SI SCHIMBAREA DE MAI JOS \*)**

In[38]:=  $\text{x0} = x /. \text{sol}[[1]]; \quad -2$   
 $\text{y0} = y /. \text{sol}[[1]]; \quad 2$

In[40]:=  $\text{a} = \text{Sqrt}\left[\frac{-\Delta}{\lambda_1 \delta}\right]$

$\text{b} = \text{Sqrt}\left[\frac{-\Delta}{\lambda_2 \delta}\right]$

Out[40]=  $\sqrt{2}$

Out[41]= 2

In[42]:=  $\text{c} = \text{If}[a < b, \sqrt{b^2 - a^2}, \sqrt{a^2 - b^2}]$

Out[42]=  $\sqrt{2}$

In[43]:= **(\* axa focala \*)**

In[44]:=  $\text{v} = \text{If}[a < b, \text{v2}, \text{v1}];$

In[45]:=  $\text{r} = 0.04;$

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In[46]:= Centru = ParametricPlot[{x0, y0} + r {Cos[t], Sin[t]},
    {t, 0, 2 Pi}, PlotStyle -> {Black, Thickness[0.01]};

In[47]:= V1 = ParametricPlot[{x0, y0} + a v1 + r {Cos[t], Sin[t]},
    {t, 0, 2 Pi}, PlotStyle -> {Magenta, Thickness[0.005]};
V2 = ParametricPlot[{x0, y0} + b v2 + r {Cos[t], Sin[t]},
    {t, 0, 2 Pi}, PlotStyle -> {Orange, Thickness[0.005]};

In[49]:= V3 = ParametricPlot[{x0, y0} - a v1 + r {Cos[t], Sin[t]},
    {t, 0, 2 Pi}, PlotStyle -> {Magenta, Thickness[0.005]};
V4 = ParametricPlot[{x0, y0} - b v2 + r {Cos[t], Sin[t]},
    {t, 0, 2 Pi}, PlotStyle -> {Orange, Thickness[0.005]};

In[51]:= (* focarele : se foloseste axa focala definita mai inainte *)

In[52]:= F1 = ParametricPlot[{x0, y0} + c v + r {Cos[t], Sin[t]},
    {t, 0, 2 Pi}, PlotStyle -> {Purple, Thickness[0.005]};
F2 = ParametricPlot[{x0, y0} - c v + r {Cos[t], Sin[t]},
    {t, 0, 2 Pi}, PlotStyle -> {Purple, Thickness[0.005]};

In[54]:= axa1 = ParametricPlot[{x0, y0} + t v1,
    {t, -a - 1, a + 1}, AspectRatio -> Automatic, PlotStyle -> Red];
axa2 = ParametricPlot[{x0, y0} + t v2, {t, -b - 1, b + 1},
    AspectRatio -> Automatic, PlotStyle -> Red];

In[56]:= CX = Graphics[Arrow[{x0, y0}, {x0, y0} + (a + .5) v1]];
CY = Graphics[Arrow[{x0, y0}, {x0, y0} + (b + 0.5) v2]];

In[58]:= axM = Graphics[{Red, Text["X", {x0, y0} + a v1 + {0.5, 0.75}]}];
axm = Graphics[{Red, Text["Y", {x0, y0} + b v2 + {-0.3, 0.5}]}];

In[60]:= centrulC = Graphics[{Red, Text["C", {x0, y0} + {0, 0.2}]}];

In[61]:= foc1 = Graphics[{Purple, Text["F", {x0, y0} + c v + {0, 0.2}]}];
foc2 = Graphics[{Purple, Text["F'", {x0, y0} - c v + {0, 0.2}]}];

In[63]:= (* reprezentare grafica *)

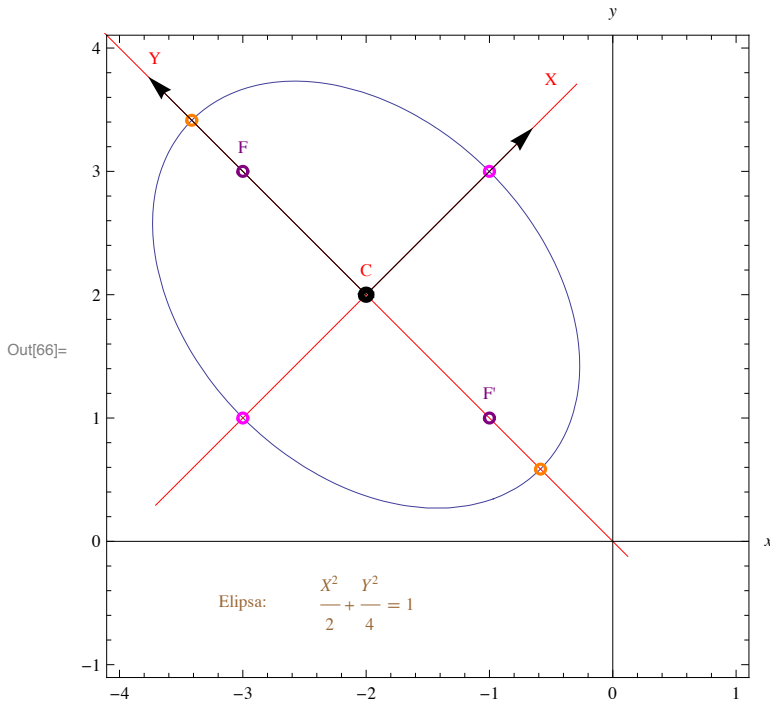
In[64]:= elipsa = ContourPlot[El[x, y] == 0, {x, -4, 1}, {y, -1, 4},
    Axes -> True, AxesLabel -> {x, y}, AspectRatio -> Automatic];

In[65]:= eqred = Graphics[{Brown,
    Text["Elipsa:", {x0 - 1, y0 - 2.5}], Text[

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1, \{x0, y0 - 2.5\}]]];$$

```

```
In[66]:= Show[elipsa, axa1, axa2, Centru, axM, axm, V1,
V2, V3, V4, eqred, CX, CY, centrulC, F1, F2, foc1, foc2]
```



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In[67]:= (*
SCHIMBAREA COORDONATELOR, PENTRU A ADUCE CONICA LA FORMA REDUSA
*)
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In[68]:= (* ROTATIA : {x, y} --> {xp, yp} *)
```

```
In[102]:= {x, y} = Transpose[{v1, v2}] . {xp, yp}
```

$$\text{Out[102]} = \left\{ \frac{x_p}{\sqrt{2}} - \frac{y_p}{\sqrt{2}}, \frac{x_p}{\sqrt{2}} + \frac{y_p}{\sqrt{2}} \right\}$$

```
In[70]:= (* ecuatia elipsei in noile coordonate xp, yp *)
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```
In[103]:= E11[xp_, yp_] := Simplify[E1[x, y]] // Expand
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```
In[104]:= E11[xp, yp]
```

$$\text{Out[104]} = 8 + 4 x_p^2 - 8 \sqrt{2} y_p + 2 y_p^2$$

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In[92]:= (* A DOUA SCHIMBARE DE COORDONATE *)
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In[117]:= (* refacem coordonatele centrului in noile coordonate xp, yp *)
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```
In[113]:= {xp0, yp0} = {v1, v2} . {x0, y0}
```

$$\text{Out[113]} = \{0, 2\sqrt{2}\}$$

```
In[118]:= (* FACEM TRANSLATIA IN CENTRU *)
```

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In[114]:= xp = X + xp0
yp = Y + yp0
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$$\text{Out[114]} = X$$

$$\text{Out[115]} = 2\sqrt{2} + Y$$

```
In[116]:= E12 = Simplify[E11[xp, yp]] // Expand
```

```
Out[116]:=  $-8 + 4 X^2 + 2 Y^2$ 
```

```

In[1]:= (* HIPERBOLA *)

(* polinomul de gradul al doilea care genereaza hiperbola *)

In[2]:= H[x_, y_] := 7 x^2 - 8 x y + y^2 - 6 x - 12 y - 9;

In[3]:= (* coeficientii formei patratice *)

In[4]:= a11 = Coefficient[H[x, y], x^2];
a12 = Coefficient[H[x, y], x y] / 2;
a22 = Coefficient[H[x, y], y^2];

In[7]:= A = {{a11, a12}, {a12, a22}};

In[8]:= MatrixForm[A]
Out[8]/MatrixForm=

$$\begin{pmatrix} 7 & -4 \\ -4 & 1 \end{pmatrix}$$


In[9]:= (* avem gen hiperbolic *)

In[10]:=  $\delta = \text{Det}[A]$ 
Out[10]= -9

In[11]:= a10 = Coefficient[Coefficient[H[x, y], x], y, 0] / 2;
a20 = Coefficient[Coefficient[H[x, y], y], x, 0] / 2;

In[13]:= a00 = Coefficient[Coefficient[H[x, y], x, 0], y, 0];

In[14]:= (*
Simbolul D este protejat, foloses DE
*)

In[15]:= DH = {{a11, a12, a10}, {a12, a22, a20}, {a10, a20, a00}}
Out[15]= {{7, -4, -3}, {-4, 1, -6}, {-3, -6, -9}}

In[16]:= MatrixForm[DH]
Out[16]/MatrixForm=

$$\begin{pmatrix} 7 & -4 & -3 \\ -4 & 1 & -6 \\ -3 & -6 & -9 \end{pmatrix}$$


In[17]:= (* avem nedegenerare *)

In[18]:=  $\Delta = \text{Det}[DH]$ 
Out[18]= -324

In[19]:= (* autovalorile si vectorii proprii matricii A *)

In[20]:=  $\lambda = \text{Eigenvalues}[A];$ 

In[21]:=  $\lambda_1 = \lambda[[1]]$ 
 $\lambda_2 = \lambda[[2]]$ 
Out[21]= 9

Out[22]= -1

In[23]:= vect = Eigenvectors[A];

In[24]:= nr1 = Sqrt[vect[[1]].vect[[1]]];
nr2 = Sqrt[vect[[2]].vect[[2]]];

```

In[26]:= **v1 = vect[[1]] / nr1**  
**v2 = vect[[2]] / nr2**

Out[26]:=  $\left\{-\frac{2}{\sqrt{5}}, \frac{1}{\sqrt{5}}\right\}$

Out[27]:=  $\left\{\frac{1}{\sqrt{5}}, \frac{2}{\sqrt{5}}\right\}$

In[28]:= **(\* orientarea \*)**

In[29]:= **or = Det[{v1, v2}]**

Out[29]= -1

In[30]:= **(\***  
**Daca orientarea eset negativa schimb semnul la v2**  
**\*)**

In[31]:= **w2 = If[or > 0, v2, -v2];**  
**v2 = w2**

Out[32]=  $\left\{-\frac{1}{\sqrt{5}}, -\frac{2}{\sqrt{5}}\right\}$

In[33]:= **(\* centrul hiperbolei \*)**

In[41]:= **eq1 = D[H[x, y], x]**  
**eq2 = D[H[x, y], y]**

Out[41]= -6 + 14 x - 8 y

Out[42]= -12 - 8 x + 2 y

In[43]:= **sol = Solve[{eq1 == 0, eq2 == 0}, {x, y}]**

Out[43]=  $\{\{x \rightarrow -3, y \rightarrow -6\}\}$

In[44]:= **x0 = x /. sol[[1]];**  
**y0 = y /. sol[[1]];**

In[46]:= **c1 =  $\frac{-\Delta}{\lambda_1 \delta}$**

**c2 =  $\frac{-\Delta}{\lambda_2 \delta}$**

Out[46]= -4

Out[47]= 36

In[48]:= **(\* daca c1 > 0 axa focala este CX \*)**

In[49]:= **a = If[c1 > 0, Sqrt[ $\frac{-\Delta}{\lambda_1 \delta}$ ], Sqrt[ $\frac{\Delta}{\lambda_1 \delta}$ ]]**

**b = If[c1 > 0, Sqrt[ $\frac{\Delta}{\lambda_2 \delta}$ ], Sqrt[ $\frac{-\Delta}{\lambda_2 \delta}$ ]]**

Out[49]= 2

Out[50]= 6



```

In[51]:= c =  $\sqrt{a^2 + b^2}$ ;

In[52]:= (*
          axa focala si d = a sau b
          *)

In[53]:= {v, d} = If[c1 > 0, {v1, a}, {v2, b}];

In[54]:= r = 0.04;

In[55]:= Centru = ParametricPlot[{x0, y0} + r {Cos[t], Sin[t]},
    {t, 0, 2 Pi}, PlotStyle -> {Black, Thickness[0.01]};

In[76]:= V1 = ParametricPlot[{x0, y0} + d v + r {Cos[t], Sin[t]},
    {t, 0, 2 Pi}, PlotStyle -> {Magenta, Thickness[0.005]};

In[74]:= V2 = ParametricPlot[{x0, y0} - d v + r {Cos[t], Sin[t]},
    {t, 0, 2 Pi}, PlotStyle -> {Magenta, Thickness[0.005]};

In[58]:= (* focarele : se foloseste axa focala definita mai inainte *)

In[59]:= F1 = ParametricPlot[{x0, y0} + c v + r {Cos[t], Sin[t]},
    {t, 0, 2 Pi}, PlotStyle -> {Purple, Thickness[0.005]};
F2 = ParametricPlot[{x0, y0} - c v + r {Cos[t], Sin[t]},
    {t, 0, 2 Pi}, PlotStyle -> {Purple, Thickness[0.005]};

In[61]:= axa1 = ParametricPlot[{x0, y0} + t v1,
    {t, -a - 1, a + 1}, AspectRatio -> Automatic, PlotStyle -> Red];
axa2 = ParametricPlot[{x0, y0} + t v2, {t, -b - 1, b + 1},
    AspectRatio -> Automatic, PlotStyle -> Red];

In[63]:= CX = Graphics[Arrow[{x0, y0}, {x0, y0} + (a + 0.5) v1]];
CY = Graphics[Arrow[{x0, y0}, {x0, y0} + (b + 1.5) v2]];

In[65]:= axM = Graphics[{Red, Text["X", {x0, y0} + a v1 + {0.5, 0.75}]}];
axm = Graphics[{Red, Text["Y", {x0, y0} + b v2 + {-0.3, 0.5}]}];

In[67]:= centrulC = Graphics[{Red, Text["C", {x0, y0} + {0, 0.2}]}];

In[68]:= foc1 = Graphics[{Purple, Text["F", {x0, y0} + c v + {0, 0.2}]}];
foc2 = Graphics[{Purple, Text["F'", {x0, y0} - c v + {0, 0.2}]}];

In[70]:= (* reprezentare grafica *)

In[71]:= Hiperbola = ContourPlot[H[x, y] == 0, {x, -10, 3}, {y, -14, 4},
    Axes -> True, AxesLabel -> {x, y}, AspectRatio -> Automatic];

In[72]:= eqred = Graphics[{Brown, Text["Hiperbola:", {x0 - 5, y0 + 5}],
    Text[ $\frac{x^2}{c1} + \frac{y^2}{c2} = 1$ , {x0 - 2, y0 + 5}]}];

```

```
In[77]:= Show[Hiperbola, axa1, axa2, Centru, axM, axm,  
V1, V2, eqred, CX, CY, centrulC, F1, F2, foc1, foc2]
```

