

**Scientific Report on the implementation of the project
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Qualitative properties of the solution set of differential inclusions

In the frame of the present project the following activities took place: documentation and research, preparation and writing scientific articles, published in ISI journals, participation at national/international conferences. The proposed objectives were completely realized. We mention that in 2014 there have been published or accepted for publishing **6 papers in ISI journals**.

The research objective for this year was: *To get new Filippov-Plis type results with applications in invariance, near viability and relaxation problems*. This research objective was realized. In the following we give a presentation of the main results obtained.

Let X be a Banach space, $A : D(A) \subseteq X \rightsquigarrow X$ an m -dissipative operator, generator of a semi-group (possibly nonlinear) $\{S(t) : \overline{D(A)} \rightarrow \overline{D(A)}; t \geq 0\}$ and $F : [0, T] \times X \rightsquigarrow X$ a nonempty valued multifunction. For $\xi \in \overline{D(A)}$ we considered the Cauchy problem

$$x'(t) \in Ax(t) + F(t, x(t)), \quad x(0) = \xi. \quad (1)$$

We say that the continuous function $x : [0, T] \rightarrow \overline{D(A)}$ is a solution of the problem (1) if it is an integral solution of the problem

$$x'(t) \in Ax(t) + f(t), \quad x(0) = \xi \in \overline{D(A)}, \quad (2)$$

where f is a Bochner integrable function with $f(t) \in F(t, x(t))$ a.e. $t \in [0, T]$. We recall that the continuous function $x(\cdot)$ is an integral solution of the problem (2) on $[0, T]$ if, for any $u \in D(A)$, $v \in Au$, $0 \leq t \leq T$, the following inequality holds:

$$\|x(t) - u\| \leq \|\xi - u\| + \int_0^t [x(\tau) - u, f(\tau) - v]_+ d\tau.$$

We mention that we denoted by $[x, y]_+$ the right directional derivative of the norm in x in direction y .

Definition. A Caratheodory function $\omega : [0, T] \times \mathbb{R}_+ \rightarrow \mathbb{R}_+$, integrally bounded on bounded sets, is called Perron function if, for any $T > 0$, the null function is the only solution on $[0, T]$ of the problem

$$r'(t) = \omega(t, r(t)), \quad r(0) = 0.$$

An important result on Perron function, used in our study, is the following:

Lemma. Suppose that $\omega : [0, T] \times \mathbb{R}_+ \rightarrow \mathbb{R}_+$ is a Perron function, integrally bounded and $(a_k)_k, (b_k)_k \subset \mathbb{R}_+$ are two sequences convergent to 0. Let $r_k(\cdot)$ be a solution of the problem

$$r'(t) = \omega(t, r(t)) + a_k, \quad r(0) = b_k.$$

Then, $\lim_{k \rightarrow \infty} r_k(t) = 0$ uniformly for any $t \in [0, T]$.

Definition. The multifunction $F : [0, T] \times X \rightsquigarrow X$ is called *one-sided Perron* (with respect to the Perron function ω) if, for any $x, y \in X$, a.e. $t \in [0, T]$ $f \in F(t, x)$, there exists $g \in F(t, y)$ such that

$$[x - y, f - g]_+ \leq \omega(t, \|x - y\|).$$

In some papers these multifunctions are called *one-sided Kamke*. The one-sided Perron condition is weaker than the Lipschitz one.

We assumed the following hypotheses:

(H₁) X is a separable Banach space and the m -dissipative operator A generates a compact semigroup $\{S(t) : \overline{D(A)} \rightarrow \overline{D(A)}; t \geq 0\}$.

(H₂) The multifunction F is almost lower semicontinuous, nonempty closed valued and has sublinear growth, i.e., there exist two positive Lebesgue integrable functions $a(\cdot)$ and $b(\cdot)$ such that

$$\|v\| \leq a(t) + b(t) \|z\|,$$

a.e. $t \in [0, T]$ and for any $z \in X$ and any $v \in F(t, z)$.

We first proved the following auxiliary result.

Proposition. Let $G : [0, T] \times X \rightsquigarrow X$ an almost lower semicontinuous multifunction. Then there exists a sequence $(\Delta_m)_m$ of compact pairwise disjoint subsets of $[0, T]$, with Lebesgue measure of the reunion $\cup_m \Delta_m$ equal to T , such that, for any $m \in \mathbb{N}^*$, $G(\cdot, \cdot)$ is lower semicontinuous on $\Delta_m \times X$.

We proved the following new Filippov-Plis result, where we weaken the Lipschitz hypothesis on the multifunction F , imposing the one-sided Perron condition.

Theorem. Assume (H₁) and (H₂). Moreover, assume that $F : [0, T] \times X \rightsquigarrow X$ is one-sided Perron (with respect to a Perron function ω) and $f : [0, T] \rightarrow \mathbb{R}$ is a positive, Lebesgue integrable function. Then, for any $\xi \in \overline{D(A)}$, $\varepsilon > 0$ and any solution $x(\cdot)$ on $[0, T]$ of the problem

$$x'(t) \in Ax(t) + F(t, x(t)) + f(t)B, \quad x(0) = \xi,$$

there exists a solution of the problem (1) on $[0, T]$, $y(\cdot)$, such that

$$\|x(t) - y(t)\| \leq r_\varepsilon(t),$$

for any $t \in [0, T]$, where $r_\varepsilon(\cdot)$ is the maximal solution of the Cauchy problem

$$r'(t) = \omega(t, r(t)) + f(t) + \varepsilon, \quad r(0) = 0.$$

A similar result was obtained in the paper [O. Cârjă, T. Donchev, V. Postolache, *Nonlinear evolution inclusions with one-sided Perron right-hand side*, J. Dyn. Control Syst., 2013] in the case when the Banach space X has a uniformly convex dual. Moreover, the continuity hypothesis imposed on the multifunction F is upper semicontinuity.

The relaxation problems consist in proving that the solution set of the initial problem (1) is dense in the solution set of the convexified (relaxed) problem:

$$x'(t) \in Ax(t) + \overline{\text{co}}F(t, x(t)), \quad x(0) = \xi. \quad (3)$$

The existing relaxation results for nonlinear differential inclusions impose Lipschitz conditions on the multifunction F . Also, these results are obtained under the supplementary hypothesis that the Banach space X is reflexive.

The relaxation results that we have established within this project hold under weaker hypotheses on F than the Lipschitz condition, more exactly we assume conditions of one-sided Perron type. Moreover, we do not impose the reflexivity of the Banach space X .

We obtained the following result:

Theorem. *Let X be a separable Banach. Suppose that (H_1) and (H_2) hold. Moreover, suppose that there exists a Perron function $\omega(\cdot, \cdot)$ such that, for any $x, y \in X$, a.e. $t \in [0, T]$ and any $f \in \overline{\text{co}}F(t, x)$, there exists $g \in F(t, y)$ such that*

$$[x - y, f - g]_+ \leq \omega(t, \|x - y\|).$$

Then, the solution set of the initial problem (1) is dense in the solution set of the problem (3).

Then, we considered the following parabolic partial derivatives equation:

$$\begin{aligned} \frac{\partial x(t, z)}{\partial t} - \Delta x(t, z) |x(t, z)|^{r-1} &\in F(t, z, x(t, z)) \\ x(t, z) &= 0 \text{ pe } [0, T] \times \Gamma \\ x(0, z) &= x_0(z) \text{ in } \Omega, \end{aligned} \quad (4)$$

where Ω is a bounded domain in \mathbb{R}^n with smooth boundary Γ and $r > (n - 2)/n$. The multifunction $F : [0, T] \times \Omega \times \mathbb{R} \rightsquigarrow \mathbb{R}$ has closed values and is lower semicontinuous in the third variable. Moreover, we supposed that the multifunction $G : [0, T] \times L^1(\Omega) \rightsquigarrow L^1(\Omega)$, defined by

$$G(t, y) = \{f \in L^1(\Omega); f(z) \in F(t, z, y(z)) \text{ a.e. on } \Omega\}$$

is measurable on $[0, T] \times L^1(\Omega)$. We showed that the problem (4) can be written in the abstract form (1). Moreover, we supposed that there exists a Perron function $\omega(\cdot, \cdot)$ such that, for any $\varphi, \psi \in L^1(\Omega)$, a.e. $t \in [0, T]$ and any $f \in \overline{\text{co}}G(t, \varphi)$, there exists $g \in G(t, \psi)$ such that

$$\begin{aligned} &\int_{\Omega_{\varphi-\psi}^+} (f(z) - g(z)) dz - \int_{\Omega_{\varphi-\psi}^-} (f(z) - g(z)) dz \pm \int_{\Omega_{\varphi-\psi}^0} (f(z) - g(z)) dz \\ &\leq \omega\left(t, \int_{\Omega} |\varphi(z) - \psi(z)| dz\right), \end{aligned}$$

where $\Omega_{\varphi-\psi}^{+(-,0)} = \{z \in \Omega; \varphi(z) - \psi(z) > (<, =) 0\}$. Then, the hypotheses of the previous theorem are satisfied. Let $x(\cdot, \cdot) \in C([0, T], L^1(\Omega))$ a generalized solution on $[0, T] \times \Omega$ of the relaxed problem

$$\begin{aligned} \frac{\partial x(t, z)}{\partial t} - \Delta x(t, z) |x(t, z)|^{r-1} &\in \overline{\text{co}}F(t, z, x(t, z)) \\ x(t, z) &= 0 \text{ on } [0, T] \times \Gamma \\ x(0, z) &= x_0(z) \text{ in } \Omega. \end{aligned}$$

Then, for $\varepsilon > 0$ we find $x_\varepsilon(\cdot, \cdot)$ a generalized solution of the problem (4) such that

$$\sup_{t \in [0, T]} \int_{\Omega} |x(t, z) - x_\varepsilon(t, z)| dz < \varepsilon.$$

The hypothesis on the multifunction F from the previous theorem is stronger than the one-sided Perron condition. In the following result we supposed that F is one-sided Perron, but we imposed a stronger condition on the space X .

Theorem. *Let X be a Banach space with univoc duality map $J(\cdot)$. Suppose that (H_1) and (H_2) hold. Moreover, suppose that $F : [0, T] \times X \rightsquigarrow X$ is one-sided Perron (with the supplementary hypothesis that, a.e. $t \in [0, T]$, $\omega(t, \cdot)$ is nondecreasing). Then, the solution set of the initial problem (1) is dense in the solution set of the problem (3).*

Moreover, we considered the differential inclusion

$$D_C^q y(t) \in F(t, y(t)), \quad y(t_0) = y_0, \quad t \in I = [t_0, T], \quad (5)$$

where F is a multifunction from $I \times \mathbb{R}^n$ to \mathbb{R}^n . We denoted by $D_C^q y$ the fractional Caputo derivative of order $0 < q < 1$, i.e.

$$D_C^q y(t) = \frac{1}{\Gamma(1-q)} \int_{t_0}^t (t-s)^{-q} \dot{u}(s) ds, \quad t_0 < t < T.$$

The absolut continuous function $y(\cdot)$ is called solution of the problem (5) if there is a measurable selection $f_y(t) \in F(t, y(t))$ such that for any $t \in I$ we have

$$y(t) = y_0 + \frac{1}{\Gamma(q)} \int_{t_0}^t (t-s)^{q-1} f_y(s) ds.$$

Consider the following hypotheses on F :

(H) $F : I \times \mathbb{R}^n \rightsquigarrow \mathbb{R}^n$ is upper semicontinuous with nonempty convex compact values. Moreover, there exists a constant α such that

$$|F(t, x)| \leq \alpha(1 + |x|), \quad \forall (t, x) \in I \times \mathbb{R}^n.$$

Let $K \subset \mathbb{R}^n$ be a closed set and let $y_0 \in K$. We studied the viability problem, i.e. the problem of existence of a solution $y(\cdot)$ for (5) such that $y(t) \in K$ for any $t \in I$.

Definition. Let $\varepsilon > 0$. An absolutely continuous function $y(\cdot)$ is called ε -solution for (5) if there exists a measurable function $g : I \rightarrow \mathbb{R}^n$ and a nondecreasing function $\sigma : I \rightarrow I$ such that

- a) $|g(t)| \leq \varepsilon$ for a.a. $t \in I$;
- b) $t - \varepsilon \leq \sigma(t) \leq t, \forall t \in I$;
- c) $y(\sigma(t)) \in K, \forall t \in I$;
- d) there exists a measurable selection $f_y(t) \in F(\sigma(t), y(t)) + g(t)B$ such that for any $t \in I$,

$$y(t) = y_0 + \frac{1}{\Gamma(q)} \int_{t_0}^t (t-s)^{q-1} f_y(s) ds.$$

Definition. We say that the pair (g, E) is tangent to $I \times K$ in $(\bar{t}, \bar{y}) \in I \times K$ if $y(\bar{t}) = \bar{y}$ and

$$\liminf_{h \rightarrow 0^+} h^{-q} d \left(\bar{y} + r(\bar{t}, g(\cdot))(h) + \frac{h^q}{\Gamma(q+1)} E, K \right) = 0.$$

We obtained the following result:

Theorem. Let $t_0 \leq \bar{t} < T$ and let $y(\cdot)$ an absolutely continuous function on $[t_0, \bar{t}]$ with $y(t_0) = y_0$. If the pair $(D_C^q y(\cdot), F(\bar{t}, y(\bar{t})))$ is tangent to $I \times K$ in $(\bar{t}, \bar{y}) \in I \times K$ then, for any $\varepsilon > 0$ there exists $\delta > 0$ and an extension $z(\cdot)$ of $y(\cdot)$ which is ε -solution of (5) on $[\bar{t}, \bar{t} + \delta]$ and such that $z(\bar{t} + \delta) \in K$.

Definition. We say that the system (5) satisfies the tangency condition in $(\bar{t}, \bar{y}) \in I \times K$ if for any $\varepsilon > 0$ there exists an ε -solution $y(\cdot)$ on $[t_0, \bar{t}]$ such that the pair $(D_C^q y(\cdot), F(\bar{t}, \bar{y}))$ to be tangent to $I \times K$ in (\bar{t}, \bar{y}) .

Theorem. Suppose that (H) holds. If the system (5) satisfies the tangency condition in any $(\bar{t}, \bar{y}) \in I \times K$, then it has a viable solution.

In 2014 there have been published or accepted for publications **6 articles in ISIjournals**, articles financially supported by the project, confirmed by the corresponding text from the Acknowledgement section.

1. T. Donchev, A. Nosheen, Fuzzy differential equations under dissipative and compactness type conditions, *Electronic Journal of Differential Equations*, Vol. 2014 (2014), No. 47, pp. 1-9. (ISI, IF=0.419).

2. E. Farkhi, T. Donchev, R. Baier, Existence of solutions for nonconvex differential inclusions of monotone type, *C.R. Acad. Bulg. Sci.*, Vol. 67 (2014), No. 3, pp. 323-330. (IS, IF=0.198, SRI=0.051).

3. T. Donchev, A. Nosheen, V. Lupulescu, Fuzzy integro-differential equations with compactness type conditions, *Hacettepe Journal of Mathematics and Statistics*, Vol. 43 (2014), No. 2, pp. 249-257. (ISI, IF=0.433, SRI=0.222).

4. O. Cârjă, T. Donchev, V. Postolache, Relaxation results for nonlinear evolution inclusions with one-sided Perron right-hand side, *Set-Valued Var. Anal.*, Vol. 22 (2014), No. 4, pp. 657-671. (ISI, IF=0.918, SRI=1.368).

5. O. Cârjă, T. Donchev, M. Rifaqat, R. Ahmed, Viability of fractional differential inclusions, *Applied Mathematics Letters*, 2014, 38, pp. 48-51. (ISI, IF=1.48, SRI=0.853).

6. T. Donchev, A. Nosheen, Value function and optimal control of differential inclusions, *Annals of the Alexandru Ioan Cuza University - Mathematics*, DOI: 10.2478/aicu-2014-0031, 2014. (ISI, IF=0.108, SRI=0.054).

IF=Impact factorul (2013) according to Web of Knowledge.

SRI=Influence score according to

http://uefiscdi.gov.ro/userfiles/file/CENAPOSS/Scor_Relativ_Influenta_2014.pdf

In order to achieve the objectives of the project, **reserach stages** have been performed to University of California Berkeley, USA, period May 18 - June 2, 2014, to University of Architecture, Civil Engineering and Geodesy, Sofia, Bulgaria, period July 7-18, 2014, to IMAR Bucuresti, Romanian Academy, period August 7-10, 2014, to University of Crete, Greece, period August 30- September 13, 2014, to Technische Universitat Wien, Austria, period: September 22 - October 9, 2014. Also, V. Postolache participated to *NetCO 2014-Conference on "New Trends in Optimal Control"*, Tours, period June 23-27, 2014.

The research results have been presented to the following conferences: *The 10th AIMS Conference on Dynamical Systems, Differential Equations and Applications*, Madrid, July 7-11, 2014 (A. I. Lazu, Estimates for large time controls), *Scientific Session of Communications, Faculty of de Mathematics*, "Al. I. Cuza" University, Iași, October 24, 2014 (A. I. Lazu, O. Cârjă, Estimates for slow controls), *Scientific Session of Communications, "O. Mayer" Mathematical Institute*, Iași, October 2014 (O. Cârjă, On the equivalence between the minimum time problem and the minimum norm problem).

Project leader,
Prof. dr. Ovidiu CÂRJĂ