

# New Finsler metrics of constant curvature

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SNCSSM 4–7 July.*

Iași, România

This work was supported by a grant of the Romanian Ministry of Research and Innovation, CCCDI-UEFISCDI, project number PN-III-P3-3.1-PM-RO-FR-2019-0234 / 1BM / 2019, within PNCDI III.

## Outline

### 1 Introduction

- Finsler metric
- The variational problem
- Flag curvature
- Projectively related metrics

### 2 New Weyl-type tensors in Finsler geometry

- Weyl-type curvature tensor for Finsler spaces
- Characterizations for Finsler metrics of constant flag curvature

### 3 New Finslerian Version of Schur Lemma

### 4 New families of projectively related Finsler metrics of constant curvature

- New Finsler metrics of negative flag curvature
- New Finsler metrics of zero flag curvature

## Outline

### 1 Introduction

Finsler metric

The variational problem

Flag curvature

Projectively related metrics

### 2 New Weyl-type tensors in Finsler geometry

Weyl-type curvature tensor for Finsler spaces

Characterizations for Finsler metrics of constant flag curvature

### 3 New Finslerian Version of Schur Lemma

### 4 New families of projectively related Finsler metrics of constant curvature

New Finsler metrics of negative flag curvature

New Finsler metrics of zero flag curvature



## Finsler metric

### Proposition

A Finsler metric on a manifold  $M$  is a function  $F : TM \rightarrow [0; \infty)$  with following properties:

- 1 Smoothness:  $F(x; y)$  is  $C^\infty$  on  $T_0M$ .
- 2 Homogeneity:  $F(x; \lambda y) = \lambda F(x; y); \lambda > 0$
- 3 Regularity/Convexity:  $(g_{ij}(x, y))$  is positive definite, where

$$g_{ij}(x, y) = \frac{1}{2}[F^2]_{y^i y^j}(x, y)$$

## Examples of Finsler structures

- a) *Riemannian metrics*:  $F(x, y) = \sqrt{g_{ij}(x)y^i y^j}$ ,  $g_{ij}$  is independent of  $y$ .
- b) *Randers metrics* are special members of Finsler metrics which have the form

$$F(x, y) = a + b = \sqrt{a_{ij}(x)y^i y^j} + b_i(x)y^i.$$

*It was introduced by Randers in his study of general relativity ([Randers-1941]). G. Randers used this metric to describe the asymmetrical space-time. It is an important model in physics.*

- c) *Square metrics*:  $F = \frac{(a + b)^2}{a}$ , where  $a$  and  $b$  are the quantities from the definition of a Randers metric.



## The arc length

Let  $F = F(x, y)$  a Finsler metric on a manifold  $M^n$  and  $\gamma : [a, b] \rightarrow \mathbb{R}$  a smooth curve on  $M$

- ① Its arc length is the integral:

$$L(\gamma) = \int_{\gamma} F(\gamma, \dot{\gamma}) dt. \quad (1)$$

- ② The First variation of the arc length is:

$$\delta L(\gamma)(V) = - \int_{\gamma} g_{\dot{\gamma}} \left( V, \nabla_{\dot{\gamma}} \frac{\dot{\gamma}}{F(\dot{\gamma})} \right) dt \quad (2)$$

### Remark

The first variation leads us to the geodesic equations associated to this metric.

## Outline

### 1 Introduction

Finsler metric

The variational problem

Flag curvature

Projectively related metrics

### 2 New Weyl-type tensors in Finsler geometry

Weyl-type curvature tensor for Finsler spaces

Characterizations for Finsler metrics of constant flag curvature

### 3 New Finslerian Version of Schur Lemma

### 4 New families of projectively related Finsler metrics of constant curvature

New Finsler metrics of negative flag curvature

New Finsler metrics of zero flag curvature



## The variational problem

A geodesic of the manifold  $(M, F)$  (parameterized by the arc length) is a critical curve of the energy function:

$$E(\gamma) = \int_a^b F^2(\gamma, \dot{\gamma}) ds.$$

Replacing the energy function by  $E = F^2$  it follows :

$$\frac{\partial E}{\partial x^i} - \frac{d}{dt} \left( \frac{\partial E}{\partial y^i} \right) = -2g_{ij} \left( \frac{d^2 x^j}{dt^2} + \frac{1}{2} g^{jl} \left( \frac{\partial^2 E}{\partial y^l \partial x^k} - \frac{\partial E}{\partial x^l} \right) \right) = 0. \quad (3)$$

If we denote  $G^j(x, y) = \frac{1}{4} g^{jl} \left( \frac{\partial^2 E}{\partial y^l \partial x^k} - \frac{\partial E}{\partial x^l} \right)$ , we have a system of  $n$  homogeneous differential equations of second order :

$$\frac{d^2 x^i}{dt^2} + 2G^i \left( x, \frac{dx}{dt} \right) = 0. \quad (4)$$

## Riemann curvature

The system (4) can be identified with a vector field given by:

$$S\left(\frac{\partial E}{\partial y^i}\right) + \frac{\partial E}{\partial x^i} = 0,$$

where

$$S = y^i \frac{\partial}{\partial x^i} - 2G^i(x, y) \frac{\partial}{\partial y^i} \quad (5)$$

The vector field written above is called geodesic spray. There are two canonical structures on  $TM$ , which we will use to develop our setting. One is the tangent structure,  $J$ , and the other one is the Liouville vector field,  $\mathcal{C}$ , locally given by

$$J = \frac{\partial}{\partial y^i} \otimes dx^i, \quad \mathcal{C} = y^i \frac{\partial}{\partial y^i}$$



## Remark

It is well known that a spray induces a nonlinear connection,  $\Gamma = [J, S]$ , with the corresponding projectors  $h$  and  $\nu$  given by

$$h := \frac{1}{2}(I + \Gamma), \quad \nu := \frac{1}{2}(I - \Gamma) \quad (6)$$

and the curvature tensor

$$R := -\frac{1}{2}[h, h].$$

We introduce the Jacobi endomorphism (the Riemann curvature tensor):

$$R_{(x,y)} := R_k^i(x, y) \frac{\partial}{\partial y^i} \otimes dx^k, \quad (7)$$

where

$$R_k^i = 2 \frac{\partial G^i}{\partial x^k} - S \left( \frac{\partial G^i}{\partial y^k} \right) - \frac{\partial G^i}{\partial y^j} \frac{\partial G^j}{\partial y^k}.$$

## Outline

### 1 Introduction

Finsler metric

The variational problem

Flag curvature

Projectively related metrics

### 2 New Weyl-type tensors in Finsler geometry

Weyl-type curvature tensor for Finsler spaces

Characterizations for Finsler metrics of constant flag curvature

### 3 New Finslerian Version of Schur Lemma

### 4 New families of projectively related Finsler metrics of constant curvature

New Finsler metrics of negative flag curvature

New Finsler metrics of zero flag curvature



## Flag curvature

Entirely analogous to the Riemannian case, we can define a quantity, that is the correspondent of the sectional curvature, named *flag curvature*.

The main instruments are:

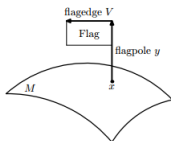
- a point  $x \in M$  that will be the place of fixing the flag,
- a flagpole given by a nonzero  $y \in T_x M$ , and
- an edge  $V \in T_x M$  transverse to the flagpole.

$$K(x, y, V) := \frac{g_{(x,y)}(R_{(x,y)}(V), V)}{g_{(x,y)}(y, y)g_{(x,y)}(V, V) - g_{(x,y)}(y, V)^2}, \quad (8)$$

is the *flag curvature* of  $(y, P)$  with  $P = \text{span}\{y, V\} \subset T_x M$ .



## Sectional curvature



### Remark

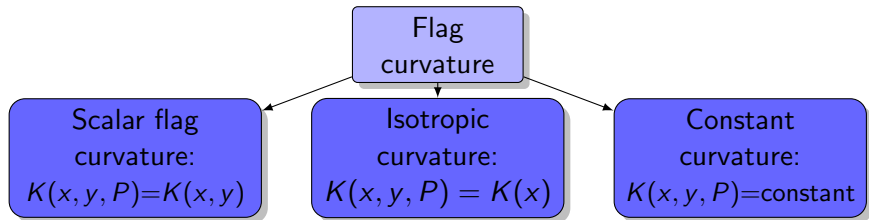
It is well known that the curvature of the flag  $(y, P)$  is independent of the choice of the flageedge  $V$ . Hence the flag curvature is usually denoted by

$$K(x, y, V) := K(x, y, P)$$

Contrast to the Riemannian case, the section  $P$  cannot completely determine the curvature in Finslerian case. One should pick a flagpole  $y \in P$  to construct a flag  $(P, y)$ , and then deduce the curvature.



## Special flag curvatures





## Jacobi endomorphism

Due to the homogeneity of the spray  $S$ , information on curvature can also be obtained through the Jacobi endomorphism, which is a 1-vector valued form defined by:

$$\Phi = \nu \circ [S, h] = R_j^i \frac{\partial}{\partial y^i} \otimes dx^j. \quad (9)$$

### Definition

The spray  $S$  is isotropic if the Jacobi endomorphism has the following form

$$\Phi = \rho J - \alpha \otimes C \Leftrightarrow R_k^i = \rho \delta_k^i - \alpha_k y^i \Leftrightarrow R_k^i = KF^2(\delta_k^i - F^{-2} g_{kq} y^q y^i),$$

where  $\rho \in C^\infty(T_0M)$  and  $\alpha = \alpha_i(x, y) dx^i \in \Lambda^1(T_0M)$ .



## Outline

### 1 Introduction

Finsler metric

The variational problem

Flag curvature

Projectively related metrics

### 2 New Weyl-type tensors in Finsler geometry

Weyl-type curvature tensor for Finsler spaces

Characterizations for Finsler metrics of constant flag curvature

### 3 New Finslerian Version of Schur Lemma

### 4 New families of projectively related Finsler metrics of constant curvature

New Finsler metrics of negative flag curvature

New Finsler metrics of zero flag curvature

## Projectively related sprays

A reparameterization preserving orientation  $t \rightarrow \tilde{t}(t)$  of the system

$$\frac{d^2 x^i}{dt^2} + 2G^i\left(x, \frac{dx^i}{dt}\right) = 0,$$

leads to a new spray  $\tilde{S} = S - 2PC$ .

The scalar function  $P \in C^\infty(TM - \{0\})$  is 1-homogeneous and it is related to the new parameter by

$$\frac{d^2 \tilde{t}}{dt^2} = P\left(x^i(t), \frac{dx^i}{dt}\right) \frac{d\tilde{t}}{dt}, \quad \frac{d\tilde{t}}{dt} > 0. \quad (10)$$

## Projectively related sprays

### Definition

Two sprays  $S$  and  $\tilde{S}$  are *projectively related* if their geodesics coincide up to an orientation preserving reparameterization.

A Finsler metric is *projectively flat* if and only if it satisfies the Hamel equation:

$$\delta_{S_0} F = d_J S_0 F - 2d_{h_0} F = 0. \quad (11)$$

In this case the projective factor  $P(x, y)$  is given by

$$P(x, y) = \frac{S_0 F}{2F}. \quad (12)$$

## Outline

### 1 Introduction

Finsler metric

The variational problem

Flag curvature

Projectively related metrics

### 2 New Weyl-type tensors in Finsler geometry

Weyl-type curvature tensor for Finsler spaces

Characterizations for Finsler metrics of constant flag curvature

### 3 New Finslerian Version of Schur Lemma

### 4 New families of projectively related Finsler metrics of constant curvature

New Finsler metrics of negative flag curvature

New Finsler metrics of zero flag curvature

## Outline

### 1 Introduction

Finsler metric

The variational problem

Flag curvature

Projectively related metrics

### 2 New Weyl-type tensors in Finsler geometry

Weyl-type curvature tensor for Finsler spaces

Characterizations for Finsler metrics of constant flag curvature

### 3 New Finslerian Version of Schur Lemma

### 4 New families of projectively related Finsler metrics of constant curvature

New Finsler metrics of negative flag curvature

New Finsler metrics of zero flag curvature



## Weyl-type curvature tensor for Finsler spaces

### Definition

Consider  $S$  a spray with Jacobi endomorphism  $\Phi$  and curvature tensor  $R$ . We define the following Weyl-type curvature tensors

$$W_0 = \Phi - \frac{1}{n-1} (\text{Tr } \Phi) J + \frac{1}{2(n-1)} d_J (\text{Tr } \Phi) \otimes \mathcal{C}. \quad (13)$$

and

$$W_1 = \frac{1}{3} [J, W_0] = R - \frac{1}{2(n-1)} d_J (\text{Tr } \Phi) \wedge J \quad (14)$$

## Outline

### 1 Introduction

Finsler metric

The variational problem

Flag curvature

Projectively related metrics

### 2 New Weyl-type tensors in Finsler geometry

Weyl-type curvature tensor for Finsler spaces

Characterizations for Finsler metrics of constant flag curvature

### 3 New Finslerian Version of Schur Lemma

### 4 New families of projectively related Finsler metrics of constant curvature

New Finsler metrics of negative flag curvature

New Finsler metrics of zero flag curvature

## Finsler metrics of constant flag curvature

### Theorem

*For a Finsler metric on a manifold of  $\dim M \geq 3$  the following conditions are equivalent:*

- ① *The Finsler metric has constant flag curvature.*
- ② *The Weyl type curvature tensor  $W_0$  vanishes.*
- ③ *The Weyl type curvature tensor  $W_1$  vanishes.*

### Theorem

*A Finsler metric on a 2-dimensional manifold has constant flag curvature if and only if the following conditions are satisfied*

- ① *The Weyl-type tensor (14) vanishes.*
- ②  $d_h \alpha = 0$ .



## Projectively related Weyl-type curvature tensors

### Lemma

Consider  $\tilde{S} = S - 2PC$  two projectively related sprays. The corresponding Weyl-curvature tensor  $W_1$  are related by

$$\tilde{W}_1 = W_1 + \frac{1}{2}\delta_S P \wedge J + d_J d_h P \otimes C. \quad (15)$$

The Weyl-type curvature tensor  $W_1$  is projectively invariant if and only if the projective factor associated to the deformation satisfies  $\delta_S P = 0$  and hence is a Hamel function.



## Lemma

Consider  $S$  and  $\tilde{S} = S - 2PC$  two projectively related isotropic sprays with the property that  $P$  is a Hamel function. Then the derivatives with respect to the horizontal projector of the semi-basic 1-forms  $\alpha$  and  $\tilde{\alpha}$  are related by

$$d_{\tilde{h}}\tilde{\alpha} = d_h\alpha - d_R P - P d_J \alpha + \alpha \wedge d_J P. \quad (16)$$

## Proposition

We consider  $F$  and  $\tilde{F}$  two projectively related Finsler metrics. If the initial metric  $F$  is of constant flag curvature and the projective factor is a Hamel function then  $\tilde{F}$  is of constant flag curvature.



## New condition for isotropic sprays

The curvature tensors  $\Phi$  and  $R$  are related by

$$3R = [J, \Phi], \quad \Phi = i_S R. \quad (17)$$

### Lemma

A spray  $S$  is isotropic if and only if there exists a semi-basic 1-form  $\xi \in \Lambda^1(T_0M)$  such that its curvature tensor  $R$  is given by:

$$R = \xi \wedge J - d_J \xi \otimes C, \quad (18)$$

where  $\xi = \frac{1}{3}(\alpha + d_J \rho)$ .

## Outline

### 1 Introduction

Finsler metric

The variational problem

Flag curvature

Projectively related metrics

### 2 New Weyl-type tensors in Finsler geometry

Weyl-type curvature tensor for Finsler spaces

Characterizations for Finsler metrics of constant flag curvature

### 3 New Finslerian Version of Schur Lemma

### 4 New families of projectively related Finsler metrics of constant curvature

New Finsler metrics of negative flag curvature

New Finsler metrics of zero flag curvature

## New Finslerian Version of Schur Lemma

### Theorem (Finslerian version of Schur's Lemma for $n \geq 2$ )

Consider  $S$  the geodesic spray of a Finsler metric  $F$ . Then  $F$  has constant curvature if and only if:

$$S \text{ is isotropic} \quad (\text{this condition is always true for } n=2); \quad (19)$$

and the curvature 1-form satisfies:

$$d_J \xi = 0; \quad (20)$$

$$d_h \xi = 0 \quad (\text{this condition is always true for } n \geq 3). \quad (21)$$

## Finslerian Version of Beltrami Theorem

### Theorem (Finslerian version of Beltrami's Theorem for $n \geq 2$ )

*Consider  $F$  and  $\tilde{F}$  two projectively related Finsler metrics. If  $\tilde{F}$  has constant curvature then  $F$  has also constant curvature if and only if the projective factor  $P$  is a Hamel function.*



## Projectively flat Randers metrics

### Proposition

*A Randers metric  $F = a + b$  is projectively flat if and only if the Riemannian metric  $a$  is projectively flat and the 1-form  $b_i dx^i$  is closed.*

### Lemma

*Let  $F = \sqrt{g_{ij}(x)y^i y^j}$  be a positive definite Finsler metric on an open domain (open and convex)  $\mathcal{U} \subset \mathbb{R}^n$  that is reducible to a Riemannian metric. Then  $F$  is projectively flat if and only if the following relation is satisfied*

$$g_{ij,l} = 2\psi_l g_{ij} + \psi_i g_{jl} + \psi_j g_{il}, \quad P(x, y) = \psi_l(x) y^l. \quad (22)$$

*In this case,  $P$  is the projective factor of  $F$ .*



## Projectively flat Randers metrics

The family of projectively flat Finsler metrics that are reducible to a Riemannian metric is given by:

$$F = \frac{\sqrt{|y|^2 + \mu (|x|^2|y|^2 - \langle x, y \rangle^2)}}{1 + \mu|x|^2}. \quad (23)$$

### Lemma

*The family of projectively flat Randers metrics of negative constant flag curvature whose projective factor is proportional to the metric is given by  $F = a + b$ , where:*

$$a = \frac{\sqrt{|y|^2 - 4c^2 (|x|^2|y|^2 - \langle x, y \rangle^2)}}{1 - 4c^2|x|^2} \text{ and } b = \frac{2c\langle x, y \rangle}{1 - 4c^2|x|^2}. \quad (24)$$

*In this case, the constant  $c$  represents the coefficient of proportionality between the projective factor and the metric.*



## Outline

### 1 Introduction

Finsler metric

The variational problem

Flag curvature

Projectively related metrics

### 2 New Weyl-type tensors in Finsler geometry

Weyl-type curvature tensor for Finsler spaces

Characterizations for Finsler metrics of constant flag curvature

### 3 New Finslerian Version of Schur Lemma

### 4 New families of projectively related Finsler metrics of constant curvature

New Finsler metrics of negative flag curvature

New Finsler metrics of zero flag curvature

## Outline

### 1 Introduction

Finsler metric

The variational problem

Flag curvature

Projectively related metrics

### 2 New Weyl-type tensors in Finsler geometry

Weyl-type curvature tensor for Finsler spaces

Characterizations for Finsler metrics of constant flag curvature

### 3 New Finslerian Version of Schur Lemma

### 4 New families of projectively related Finsler metrics of constant curvature

New Finsler metrics of negative flag curvature

New Finsler metrics of zero flag curvature



## A new family of projectively related Finsler metrics obtained through a Randers deformation

We consider  $F$  given by (24). We make a Randers deformation of the metric

$$F \rightarrow \tilde{F} = F + \tilde{b}, \quad (25)$$

where  $\tilde{b}$  is given by  $\tilde{b}(x, y) = b_i(x)y^i$ . Since  $\delta_S \tilde{F} = 0 \Leftrightarrow \delta_S \tilde{b} = 0$ , it follows that  $F$  and  $\tilde{F}$  are projectively related.

The projective factor is given by:

$$P = \frac{S(\tilde{F})}{2\tilde{F}} = \frac{S(F + \tilde{b})}{2(F + \tilde{b})} = \frac{S(\tilde{b})}{2(F + \tilde{b})}. \quad (26)$$



## New families of Finsler metrics of negative flag curvature

We assume that  $P = \nu \tilde{b}$ ,  $\nu \in \mathbb{R}$  and we get

$$S_0 \tilde{b} - 2\nu \tilde{b}^2 = 0. \quad (27)$$

Finally we got that the 1-form  $\tilde{b}$  is given by

$$\tilde{b}(x, y) = \frac{\langle e, y \rangle}{4\nu^2 (\langle e, x \rangle + f)}, \quad f > 0, |e| < 1. \quad (28)$$

Therefore, the metric obtained through this deformation is

$$\tilde{F} = \frac{\sqrt{|y|^2 - 4\nu^2 (|x|^2|y|^2 - \langle x, y \rangle^2)}}{1 - 4\nu^2|x|^2} - \frac{2\nu\langle x, y \rangle}{1 - 4\nu^2|x|^2} + \frac{\langle e, y \rangle}{4\nu^2 (\langle e, x \rangle + f)}, \quad (29)$$

with  $\tilde{\kappa} = -c^2$ .

## Outline

### 1 Introduction

Finsler metric

The variational problem

Flag curvature

Projectively related metrics

### 2 New Weyl-type tensors in Finsler geometry

Weyl-type curvature tensor for Finsler spaces

Characterizations for Finsler metrics of constant flag curvature

### 3 New Finslerian Version of Schur Lemma

### 4 New families of projectively related Finsler metrics of constant curvature

New Finsler metrics of negative flag curvature

New Finsler metrics of zero flag curvature



## New Finsler metrics of zero flag curvature inspired by squared metrics

We consider the following deformation of the Finsler metric (24):

$$\tilde{F} = f(x) \frac{F^2}{a}, \text{ where } f \text{ is a positive function and } a \text{ is given by (24).} \quad (30)$$

### Lemma

Let  $F = a + b$  a Randers metric. Then  $\tilde{F} = f(x) \frac{F^2}{a}$  is projectively related to  $F$  if and only if the following relation is satisfied

$$\frac{F^2}{a} d_h f - S(f) d_J \left( \frac{F^2}{a} \right) + f S(a) d_J \left( \frac{F^2}{a^2} \right) = 0. \quad (31)$$



## A new Finsler metric of zero flag curvature

$$P = \frac{S(f)}{2f} - \frac{S_0a - 2cFa}{2a} = \frac{Sf}{2f} - \frac{4cab - 2cFa}{2a} = \frac{S_0f}{2f} - 2cb + cF. \quad (32)$$

We notice that

$$\delta_S P = \delta_S \left( \frac{S_0f}{2f} - 2cb + cF \right) = \delta_S \left( \frac{S_0f}{2f} \right) \quad (33)$$

We assume that  $S_0f = 4cfb$  and we get

$$\tilde{F} = \frac{\eta(\sqrt{|y|^2 - 4c^2(|x|^2|y|^2 - \langle x, y \rangle^2)} + 2c\langle x, y \rangle)^2}{(1 - 4c^2|x|^2)^2 \sqrt{|y|^2 - 4c^2(|x|^2|y|^2 - \langle x, y \rangle^2)}}, \quad \eta \in \mathbb{R}^+, \quad (34)$$

with  $\tilde{\kappa} = 0$ .



## A new metric of zero flag curvature obtained through a conformal transformation

### Lemma

We consider  $F$  and  $\tilde{F}$  two projectively flat Finsler metrics and  $\bar{F} = g(x)\tilde{F} + \frac{f(y)}{F}\tilde{F}$  a metric obtained by a multiplication of the projectively flat metric  $\tilde{F}$  with the 0-homogeneous function  $g(x) + \frac{f(y)}{F}$ , where  $g$  and  $f$  are considered such that  $\bar{F}$  is positive. Then  $\bar{F}$  is projectively flat if and only if the following relation is satisfied

$$\begin{aligned} & \tilde{F}d_{h_0}g - S_0gd_J\tilde{F} - \frac{S_0fd_J\tilde{F}}{F} + \frac{\tilde{F}S_0fd_JF}{F^2} - \frac{S_0\tilde{F}d_Jf}{F} + \frac{fS_0\tilde{F}d_JF}{F^2} + \frac{\tilde{F}S_0Fd_Jf}{F^2} \\ & + \frac{fS_0Fd_J\tilde{F}}{F^2} - \frac{2f\tilde{F}S_0Fd_JF}{F^3} = 0. \end{aligned}$$

(35)



## New Finsler metric of zero flag curvature

$$P = \frac{S_0 \bar{F}}{2\bar{F}} = \frac{S_0 g \cdot \tilde{F} + g S_0 \tilde{F} + \frac{S_0 f}{F} \tilde{F} + \frac{f S_0 \tilde{F}}{F} - f \frac{\tilde{F}}{F^2} S_0 F}{2 \left( g \tilde{F} + \frac{f}{F} \tilde{F} \right)} \quad (36)$$

We recall that  $F$  and  $\tilde{F}$  are two projectively flat Finsler metrics for which  $S_0 F = 2cF^2$  and  $S_0 \tilde{F} = 4cF\tilde{F}$ .

Therefore, (36) becomes:

$$P = \frac{S_0 g \cdot \tilde{F} + \frac{S_0 f}{F} \tilde{F} - 2cf\tilde{F}}{2 \left( g \tilde{F} + \frac{f}{F} \tilde{F} \right)} + 2cF. \quad (37)$$



## New Finsler metric of zero flag curvature

Taking into account the conditions imposed on the functions  $f$  and  $g$  it follows that we can make the following extra assumption

$$S_0g = 2cf \text{ and } S_0f = 0. \quad (38)$$





With the assumptions considered in (38) we get that the projective factor associated is

$$P = 2cF, \quad (39)$$

which is a Hamel function. We can write now the expression for the new metric as follows

$$\bar{F} = \frac{\eta(\sqrt{|y|^2 - 4c^2(|x|^2|y|^2 - \langle x, y \rangle^2)} + 2c\langle x, y \rangle)^2}{(1 - 4c^2|x|^2)^2 \sqrt{|y|^2 - 4c^2(|x|^2|y|^2 - \langle x, y \rangle^2)}} \cdot \left( 2c\langle a, x \rangle + e + \frac{\langle a, y \rangle}{\frac{\sqrt{|y|^2 - 4c^2(|x|^2|y|^2 - \langle x, y \rangle^2)}}{1 - 4c^2|x|^2} + \frac{2c\langle x, y \rangle}{1 - 4c^2|x|^2}} \right). \quad (40)$$

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*Thank you*